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SOME EXACT SOLUTIONS OF TWO-DIMENSIONAL
FLOWS OF COMPRESSIBLE FLUID
WITH HODOGRAPH METHOD

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SUMMARY

A suggestion is given for classifying the compressible potential flows according to the location and number of singularities in the subsonic region of the hodograph plane, which seems to offer a convenient criterion for systematic investigation of these flows with Chaplygin's original method. The primary object of the paper is to present and analyze a few useful solutions of compressible potential flow with the exact gas law. These solutions include flows about convex corners which are the same type given by Kraft and Dibble. These flows belong to the same class as that of Ringleb, that is, they have a hodograph singularity at the origin. For this reason they are called generalized Ringleb flows. Furthermore, the exact solution of compressible flow through a particular contracting channel is given. This flow is characterized in the hodograph by a source corresponding to incoming velocity and a sink corresponding to throat velocity. The channel flow near the point of inflection of the boundary is given in detail.

INTRODUCTION

The hodograph method as applied to the two-dimensional potential flow of compressible perfect fluid was demonstrated by Molenbroek (reference 1) in 1890 and by Chaplygin (reference 2) in 1904, and has lately been formulated more extensively by Tsien and Kuo (reference 3), Lighthill (reference 4), Cherry (reference 5), Chang (reference 6), and so forth. Although the mathematical theory of the method is well established, very few exact solutions of physically interesting flows have been found. Solutions have been found by Kármán and Tsien (e.g., reference 7) and Guderley and Yoshihara (reference 8) using hypothetical gas laws. There is danger that important physical features may be lost in such approximate solutions even though the analysis is often very much simplified. It would seem worth while to obtain as many compressible flows as possible with the exact gas law.

There are a number of difficulties which impede the investigators in the search for exact solutions for compressible flow. In general, there are singularities in the flow field which make analytic continuation necessary. The analytic continuation even across a simple pole is complicated for compressible flow. It would be a formidable mathematical task to find the analytic continuation across the higher-order singularities. Lighthill's (reference 4) or Cherry's (reference 5) method of expressing Chaplygin's function of complex eigenvalue in terms of a series of Chaplygin's functions of positive integral values sounds fine analytically; however, in practice the numerical calculation is rather impractical.

Huckel's tables (reference 9) are the only satisfactory ones on the Chaplygin function (which is, in effect, a variety of hypergeometric functions of the Mach number depending on two parameters, i.e., the specific heat ratio γ and the eigenvalue n) covering a large enough range of n with small enough intervals of Mach number M to determine the necessary information for a compressible flow of the perfect gas with $\gamma = 1.4$. Even with Huckel's tables, the range and intervals of Mach number and of eigenvalue n are too limited for calculating the flow in many cases. The series solution representing the stream function in the hodograph plane converges very slowly near flow singularities, if they are not at the origin. Many more terms (corresponding to larger values of n) than those available in the tables are needed in order to obtain a closer estimation to flow behavior. Also the existing methods of summing a slowly converging series are rather inadequate to handle the present problem. The unpublished method of Shanks (reference 10) for summing such series seems a step forward, and it was certainly helpful for the present work.

For very large values of n, the asymptotic solutions of the Chaplygin function in the sense of Cherry (reference 11) require tables of Bessel functions of both the first and second kind. Although many Bessel functions have been calculated by the Harvard Computation Laboratory, National Bureau of Standards, and others, the tabulation of Bessel functions of the second kind is quite incomplete.

To avoid the above difficulties, the authors attempt to show with the hodograph method a few simple solutions of compressible flow which require no analytic continuation and are just within the capacity of a desk computer and the range of existing tables. It is well-known that the simple Ringleb solution (reference 12) on the curved convergent-divergent nozzle shows many interesting properties of smooth transonic potential flow. In principle, this compressible Ringleb flow is deduced from the incompressible flow turning around a semi-infinite thin plate. This corresponds to a doublet at the hodograph origin.

The authors are indebted to Dr. G. S. S. Ludford for obtaining a copy of Shanks' paper.

Kraft and Dibble (reference 13) have studied a more general class of hodograph flows with a multiple pole at the origin and boundaries composed of constant θ and constant velocity magnitude q. Each flow then covers a sector of a circle about the origin in the hodograph plane. The Ringleb flow is a special case of this class of flows, as are the generalized Ringleb flows to be discussed later. Among others, Kraft and Dibble give the detailed smooth flow pattern for flow turning about a 60° corner angle which is obtained numerically with the differential analyzer. The solid boundary is composed of straight lines and a rounded corner, where the velocity magnitude is constant everywhere on the corner.

Corresponding to multiple-order singularities at the origin, a family of compressible flows are derived here from the incompressible flow about a sharp convex corner. Such an approach had been briefly indicated in reference 14. These flows belong to the class of Ringleb flows and are therefore called generalized Ringleb flows. Although much had been learned from the original Ringleb flow and the flows of Kraft and Dibble, there still remained some unexplored features that such a family of flows might illuminate:

- (1) The effect of the size of the corner angle upon the maximum possible velocity for smooth isentropic flow
- (2) The nature and influence of the limiting line for different members of this flow family
- (3) The identification of all the pieces of hodograph flow with the flow in the physical plane

The present treatment attempts to cover this unknown ground with the simple calculating tools available to an ordinary researcher. There are still a number of things which call for further investigation.

Another interesting example is the compressible flow through a two-dimensional contraction channel. The imposed conditions on the flow are: (a) The low-velocity incoming flow is uniform and parallel to the x-axis and (b) the outgoing flow is uniform, parallel to the axis, and of higher speed. So far, no exact solution for such a compressible channel flow is available. In order to show the essential features without becoming involved in too complicated an analysis, the ratio of incoming to outgoing velocity in the channel flow of the incompressible fluid (reference 15) is assumed equal to 1/2, (i.e., ratio of inlet area and throat area is 2:1) without specifying the geometry of the channel. The domain of flow in the hodograph is restricted to lie within the annular region between the hodograph source corresponding to the incoming flow and the hodograph sink corresponding to the outgoing flow. Consequently, the entire flow in the hodograph can be represented by a single series without the complication of analytic continuation. There is,

however, a disadvantage due to this choice; namely, the channel becomes infinitely long. In consequence it is difficult to calculate the whole flow field numerically and so only the channel boundary is given and the channel flow in the neighborhood of the point of inflection is shown in detail.

An amplification of Huckel's tables was made for the present calculation and is included in the report as tables 1 to 4. These tables were calculated with the ordinary desk computer and are expected to be accurate to the third place. (See appendix A.)

This paper offers a simple means of classifying potential compressible flow according to the location and number of the hodograph singularities in the subsonic domain instead of the singularities in the physical plane. Examples are given for each group, some well-known, some new. The flows are restricted to only those which can be treated with Chaplygin's method (reference 2). Perhaps such a classification will lead to systematic investigation of useful solutions of hodograph equations in the future.

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CLASSIFICATION OF TYPES OF FLOWS

ACCORDING TO HODOGRAPH SINGULARITIES

The laws of mass and momentum conservation of the isentropic, irrotational flow of an inviscid, compressible fluid can be expressed in terms of a single differential equation (reference 3):

$$(a^2 - u^2)\psi_{xx} - 2uv\psi_{xy} + (a^2 - v^2)\psi_{yy} = 0$$
 (1)

where x and y are rectangular coordinates, u and v are the respective velocity components, a is the local sound velocity, and $\,\Psi\,$ is the stream function defined by

$$u = \frac{\rho_0}{\rho} \psi_y$$

$$v = -\frac{\rho_0}{\rho} \psi_x$$
(2)

Here ρ is the local density and the subscript o refers to the stagnation condition. (A list of symbols is given in appendix B.)

Introduce the velocity magnitude $q=\sqrt{u^2+v^2}$ and the constant ultimate velocity $q_m=a_0\sqrt{\frac{2}{\gamma-1}}$. It can be shown that both a and ρ are unique functions of velocity magnitude q:

$$\frac{a^{2}}{a_{0}^{2}} = 1 - \frac{q^{2}}{q_{m}^{2}} = 1 - \tau$$

$$\frac{\rho}{\rho_{0}} = (1 - \tau)^{\beta}$$
(3)

where $\tau = q^2/q_m^2$ (0 $\leq \tau \leq 1$) and $\beta = 1/(\gamma - 1)$.

For given boundary conditions, equation (1), being nonlinear, is very difficult to solve. Chaplygin (reference 2) presumably saw that the coefficients of the high-order derivatives of ψ contain only functions of u and v which are in turn related to the first derivatives of ψ . Consequently, he succeeds in the use of q and θ as independent variables to express the equation in the hodograph plane as

$$q^{2}\psi_{qq} + (M^{2} + 1)q\psi_{q} + (1 - M^{2})\psi_{\theta\theta} = 0$$
 (4)

where M=q/a is the Mach number, being a function of q but independent of θ . The important gain of the equation in this form is its linearity, the separability of variables, and the feasible superposition of particular solutions. It is elliptic in character if M < 1 and hyperbolic if M > 1. The particular solution chosen by Chaplygin is

$$\psi(q,\theta) = \psi_n(q)e^{in\theta}$$
 (5)

where n is real. Then $\Psi_n(q)$ satisfies an ordinary differential equation where prime means differentiation with respect to q:

$$q^{2}\psi_{n}''' + (1 + M^{2})q\psi_{n}' - n^{2}(1 - M^{2})\psi_{n} = 0$$
 (6)

whose solution is

$$\psi_{\mathbf{n}}(\mathbf{q}) = \mathbf{q}^{\mathbf{n}} \mathbf{F} \left(\mathbf{a_n}, \mathbf{b_n}; \ \mathbf{c_n}; \ \frac{\mathbf{q}^2}{\mathbf{q_m}^2} \right)$$
 (7)

where

$$a_{n} + b_{n} = n - \beta$$

$$a_{n}b_{n} = -\frac{n(n+1)}{2} \beta$$

$$c_{n} = n + 1$$
(8)

and

$$F\left(a_{n},b_{n}; c_{n}; \frac{q^{2}}{q_{m}^{2}}\right)$$
 (9)

is a hypergeometric function. Since $F\left(a_n,b_n;\ c_n;\ \frac{q^2}{q_m^2}\right)$ depends only on n and γ instead of three parameters, it may be called the Chaplygin function. For M = 0, the incompressible case, F = 1 and

 $\Psi(q,\theta)=q^ne^{in\theta}$. Note that $e^{in\theta}$ remains the same for compressible and incompressible flow. This means that, for this particular solution, compressibility has no influence on the velocity phase angle θ . For each particular value of γ and n, the compressibility influences only the velocity magnitude, that is,

$$q^n \longrightarrow q^n F\left(a_n, b_n; c_n; \frac{q^2}{q_m^2}\right)$$
 (10)

This point leads Chaplygin to his famous method: If the flow or stream function of the incompressible fluid is known in the hodograph plane and is expressible in a power series of $\, q$, a corresponding compressible flow in the hodograph plane can be obtained by replacing $\, q^n \,$ in each

term of the power series by
$$q^n F\left(a_n, b_n; c_n; \frac{q^2}{q_m^2}\right)$$
. It should be noted

that there is a marked difference in the valid domain of the compressible and incompressible hodograph planes. The incompressible hodograph domain is infinite in extent while the compressible hodograph domain is restricted within the circle of ultimate velocity \mathbf{q}_m . If the two streamlines for the same value of ψ in the compressible flow are compared, the two streamlines are not the same geometrical shape. The larger the Mach number, the more the distortion.

Chaplygin (reference 2) shows that this hodograph flow can be uniquely mapped to the physical plane as long as the flow is nowhere supersonic. Later investigators show that as long as the Jacobian $\partial(x,y)/\partial(q,\theta)$ is not singular, the hodograph flow can always be mapped conformally back to the physical plane. The boundary line where $\partial(x,y)/\partial(q,\theta)=0$ is called the limiting line by Tollmien (reference 16) and Tsien (reference 17). Thus, in the compressible flow, the valid hodograph domain is further restricted by the limiting line, which lies inside the circle of ultimate velocity q_m in the supersonic region. Only the hodograph flow within the limiting line can be meaningful flow in the physical plane. However, if only isentropic flow is of interest, the hodograph flow should be further confined to the region within the streamline first touched by the limiting line.

There is one complicated feature with this method, that is, if the incompressible hodograph flow has one or more regular singularities in the flow region, one power series is required for each annular region of convergence between the singularities. Of course, the analytic continuation is required across the singularities. However, in applying

the compressibility effect with the hypergeometric functions, the corresponding analytic continuation is very difficult to find. Cherry (reference 5) and Lighthill (reference 4) have contributed a great deal on this point for flows without circulation. As far as flows with circulation are concerned, that problem is far from being solved.

So far, the boundary conditions of equation (1) have not been discussed. The situation cannot be handled for general physical boundary conditions or even for general hodograph boundary conditions. Chaplygin's method of particular solution can treat only the simplest hodograph boundary conditions; that is, where the boundaries are composed of lines of constant θ and circular arcs of constant q, such as the flow through an aperture with inclined straight walls as shown in reference 6. Consequently, the flows can be classified only by means of the hodograph singularities. According to the order of simplicity of solution, the flow solutions are classified into the following categories:

(1) One singularity located at hodograph origin.

The simplest singularity of this type is a source at the hodograph origin, the stream function of which is $\psi=-\theta$ as shown in figure 1(a) for the incompressible flow. The streamlines are straight radial lines extending from the origin to infinity. It is interesting that this hodograph source corresponds to a physical sink which has streamlines coming from infinity and running radially into the origin. However, for the compressible flow with hodograph source at the origin (fig. 1(b)) the streamlines are tangent to the characteristics at the sonic line. The sonic circle is the limiting line and the flow cannot continue beyond this circle in the hodograph. In the physical plane, it is impossible to continue the flow inside the sonic circle.

Figures 2(a) and 2(b) show the vortex both for the incompressible flow and the compressible flow in the hodograph and physical planes. Note that a vortex in the hodograph becomes a vortex also in the physical plane. Both vortices have the same sense, and the flow near the hodograph origin corresponds to the physical flow far away and vice versa. Although the incompressible flow extends to infinity in both the hodograph and physical planes, the compressible flow is restricted within the circle of ultimate velocity $\mathbf{q}_{\mathbf{m}}$ in the hodograph plane and outside the ultimate velocity circle in the physical plane. This is due to the fact that the ultimate-velocity circle is a streamline which is tangent to all the characteristics and is thus the limiting line.

These simple flows are well-known. They give a clear demonstration of the principles involved.

A combination of hodograph source and vortex at the origin will have the limiting line occurring on a circle about the origin with

radius between the sonic and ultimate velocity. This case has been fully explored by Taylor (reference 18). The Ringleb flow (reference 12) and the generalized Ringleb flow as given in this paper are some examples of other types of singularities at the hodograph origin. It is interesting to see that this group can produce transonic flows.

This is the simplest in analysis of the four groups given, because the compressibility effect has no influence on the local character of the singularity at the origin.

(2) One singularity located at the hodograph origin and one or more located on the circle of maximum velocity which is not greater than sonic velocity.

Flows of this type are the impinging jet of subsonic velocity (reference 19 gives the incompressible case) and flow through an aperture (references 2 and 6). Impinging jets can be treated for the compressible flow without difficulty. This group can produce subsonic or at most sonic flows. The compressibility effect will distort the local streamlines of the outer hodograph singularities from the corresponding incompressible ones.

(3) Two singularities, one located at the lowest speed $(q_1 > 0)$ and the other located at the highest speed $(q_2 \le a)$ where the region of hodograph flow is located in the annular region between the singularities.

There are a number of such flows for various contracting channels. One example is discussed in this report. This group can also produce only subsonic or at most sonic flows. It is not too difficult to treat if the incompressible hodograph flow can be expressed analytically. At both singularities the compressibility effect will distort the streamlines locally from the incompressible flow pattern.

(4) One or more hodograph singularities all located inside the flow domain with no streamline tangent to a characteristic.

Hodograph flow corresponding to Borda's mouthpiece (the incompressible case is given in reference 19) may be considered as an example. The hodograph flow corresponding to the physical flow past a circle is another example except this requires a two-sheeted Riemann surface (reference 5).

The flows of this type are much more complicated. The compressibility effect will distort the streamlines in the neighborhood of the singularity if not at the origin. Analytic continuation is always necessary. However, this group could produce transonic flows about a closed body, if no limiting line occurs.

This classification by no means covers all the compressible flows that can be treated by the hodograph methods, being restricted to only those potential flows where Chaplygin's method may be applied. There are many other types of singularities including some located in the supersonic region which extend the flow field into the supersonic range, but such cases are out of the scope of the present treatment.

GENERALIZED RINGLEB FLOW

It is known that a doublet at the origin of the hodograph plane corresponds to an incompressible flow turning about a semi-infinite thin plate in the physical plane. In 1940, Ringleb (reference 12) was the first one to modify such a hodograph doublet with a compressibility effect. He found the streamlines near the tip of the plate could be conformally mapped back to the physical plane only so long as the maximum flow velocity q on the streamline never reaches 1.67 times the stagnation sound velocity $a_0(M = 2.5)$. For higher velocity, the Jacobian $\partial(x,y)/\partial(q,\theta)$ of the transformation relation between the hodograph plane and the physical plane becomes zero along a curved line and the mapping is no longer conformal. At this line the streamlines will form cusps and double back on themselves. No physical flow can be attached to such streamlines. Earlier than 1940, the Clausers (reference 20) found this feature for compressible flow turning within a concave corner. They further discuss the singular behavior of the streamlines and show that the locus of the cusps in the physical plane corresponds to the locus of the points of tangency of the streamlines and the characteristic curves in the hodograph plane. The acceleration is infinite at the cusps. This flow leads to the concepts of the forbidden region of Von Kármán (reference 7) and the limiting lines of Tollmien (reference 16) and Tsien (reference 17). Furthermore, Ringleb was the first to show that smooth transonic flow was possible in a convergent-diverent nozzle formed by the streamlines in the so-called "Ringleb flow."

Figure 3(a) shows that incompressible flow turning a convex corner of angle $2\pi - \alpha$ corresponds to a lemniscate family within the two straight-line asymptotes which contain the angle $\alpha - \pi$ in the hodograph. It is well-known that this incompressible flow can be expressed very simply analytically both in the physical plane and in the hodograph plane. At the sharp convex corner the local flow will reach infinite velocity corresponding to the assumed infinite sound velocity of the incompressible fluid. This flow covers a semi-infinite region in the hodograph bounded by the angle $\alpha - \pi$. However, if the compressibility of the fluid is considered, the sound velocity becomes finite. The possible flow in the hodograph plane is confined within a circle of ultimate velocity q_m and the angle $\alpha - \pi$. Actually, the flow will

break down somewhat before the velocity reaches $\,\mathbf{q}_{m}\,$ owing to the existence of the limiting line.

As mentioned previously, Kraft and Dibble have studied these flows around convex corners, devoting particular attention to the use of a 60° corner. In the present paper a number of additional examples are given and such features as the location and shape of the limiting lines are studied in greater detail.

Consider the incompressible flow whose complex potential is represented by the analytic function

$$w_i = z^m \tag{11}$$

where $w_1=p_1'+i\psi_1'$ and $z=re^{i\Theta}$ as usually defined. Here Θ is restricted to $0 \le \Theta < 2\pi$ which means only the first sheet of the z-plane is considered. The stream function then is

$$\psi_{i} = r^{m} \sin m_{\Theta} \tag{12}$$

which gives $\psi_i=0$ when $\theta=0$ and π/m . Thus equation (11) represents the complex potential of a corner flow. Introduce the angle which the flow turns as

$$\alpha = \frac{\pi}{m} \tag{13}$$

Then it is apparent that the corner angle is 2π - α . Consider now only the flow passing a convex corner which corresponds to $\pi < \alpha \le 2\pi$ or $1 > m \ge 1/2$.

The complex velocity is

$$\overline{q}_{i} = \left| q_{i} \right| e^{-i\theta} = \frac{dw_{i}}{dz} = mz^{m-1} = mr^{m-1}e^{i(m-1)\Theta}$$
(14)

which shows $\overline{q}_1 \longrightarrow \infty$ as $z \longrightarrow 0$ and $\overline{q}_1 \longrightarrow 0$ as $z \longrightarrow \infty$ for convex corners. Conversely,

$$z = \left(\frac{\overline{q}_{i}}{m}\right)^{\frac{1}{m-1}} \tag{15}$$

Thus the flow about the convex corner can be represented in the hodograph plane as

$$w_{i} = \left(\frac{\overline{q}_{i}}{m}\right)^{\frac{m}{m-1}} \tag{16}$$

The corresponding stream function in the hodograph plane is

$$\Psi_{i} = -\left(\frac{q_{i}}{m}\right)^{\frac{m}{m-1}} \sin \frac{m}{m-1} \theta \tag{17}$$

The streamline $\psi_i=0$ corresponds to the boundary of a concave corner in the hodograph where $\theta=\alpha-\pi\le\pi$. The streamlines correspond to leaves of one branch of the lemniscate bounded by that angle, all of which are tangent at the origin. Note that the flow in the physical plane occupies a region of angle α while the flow in the hodograph occupies a region of angle $\alpha-\pi$.

The corner flow has only one singularity, located at the hodograph origin. For the case $\alpha=3\pi/2$, the hodograph singularity is a quadrupole derived from two sources on a diagonal at 45° and two sinks at -45° . For flow turning around a semi-infinite flat plate $\alpha=2\pi$, there is a doublet at the origin. These are examples of the first class of hodograph singularities.

Now, following Chaplygin, introduce the compressibility effect into the hodograph equation (equation (4)). Here $n=\pi/(\pi-\alpha)$. The solution ψ_n from equation (7) gives

$$\psi_{\frac{\pi}{\pi-\alpha}}(q) = q^{\frac{\pi}{\pi-\alpha}} F\left(a,b; c; \frac{q^2}{q_m^2}\right)$$
 (18)

where

$$a + b = \frac{\pi}{\pi - \alpha} - \beta$$

$$ab = -\frac{\beta}{2} \frac{\pi}{\pi - \alpha} \left(\frac{2\pi - \alpha}{\pi - \alpha} \right)$$

$$c = \frac{2\pi - \alpha}{\pi - \alpha}$$

The hypergeometric function $F\left(a,b;\ c;\ \frac{q^2}{q_m^2}\right)$ can be represented by the infinite series

$$F\left(a,b; c; \frac{q^2}{q_m^2}\right) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)\Gamma(b+k)}{\Gamma(c+k)} \frac{1}{k!} \left(\frac{q}{q_m}\right)^{2k}$$
(19)

This series becomes finite if a or b is a negative integer. This fact is utilized for the present numerical calculations.

This solution, equation (18), is convergent for all values of $q < q_m$ and passes continuously into $q^{\frac{\pi}{\pi-\alpha}}$ as $M \longrightarrow 0$ as ensured by equation (10). Introduce $\tau = q^2/q_m^2$. Then this can be written

$$\psi(q) = \left(\frac{1}{q_m}\right)^{\frac{\pi}{\alpha-\pi}} \tau^{\frac{1}{2}} \frac{\pi}{\pi-\alpha} F(a,b; c; \tau)$$
 (20)

The solution of $\psi(q,\theta)$ in equation (4) can be written as

$$\Psi = A \left(\frac{1}{q_m}\right)^{\frac{\pi}{\alpha - \pi}} \tau^{\frac{1}{2} \frac{\pi}{\pi - \alpha}} F(a,b; c; \tau) \sin \frac{\pi}{\alpha - \pi} \theta$$
 (21)

Imposing the condition that $\psi \longrightarrow \psi_i$ in equation (17) as M \longrightarrow 0, A can be determined as

$$A = \left(\frac{\pi}{\alpha}\right)^{\frac{\pi}{\alpha - \pi}} \tag{22}$$

Thus

$$\psi = \left(\frac{\pi}{\alpha q_{m}}\right)^{\frac{\pi}{\alpha - \pi}} \frac{\frac{1}{2} \frac{\pi}{\pi - \alpha}}{\tau} F(a,b; c; \tau) \sin \frac{\pi}{\alpha - \pi} \theta$$
 (23)

which shows the same hodograph singularity at the origin as the incompressible case.

Physical Coordinates

As soon as ψ is known in the hodograph plane, each point in $\frac{\pi}{\pi-\alpha}$

the hodograph can be transformed back to the physical plane by the following relations:

$$x - x_{0} = -\frac{\frac{q\psi}{\pi - \alpha} + \frac{\pi}{\alpha - \pi} \psi}{2\tau^{1/2} (1 - \tau)^{\beta}} \frac{\cos\left(1 - \frac{\pi}{\alpha - \pi}\right)\theta}{1 - \frac{\pi}{\alpha - \pi}} + \frac{q\psi}{\frac{\pi}{\pi - \alpha}} \frac{-\frac{\pi}{\alpha - \pi} \psi}{\frac{\pi}{\pi - \alpha}} \frac{\cos\left(1 + \frac{\pi}{\alpha - \pi}\right)\theta}{1 + \frac{\pi}{\alpha - \pi}}$$

$$y - y_{0} = -\frac{\frac{q\psi}{\pi} + \frac{\pi}{\alpha - \pi} \psi}{2\tau^{1/2} (1 - \tau)^{\beta}} \frac{\sin\left(1 - \frac{\pi}{\alpha - \pi}\right)\theta}{1 - \frac{\pi}{\alpha - \pi}} + \frac{q\psi}{2\tau^{1/2} (1 - \tau)^{\beta}} \frac{\sin\left(1 + \frac{\pi}{\alpha - \pi}\right)\theta}{1 - \frac{\pi}{\alpha - \pi}} + \frac{q\psi}{\frac{\pi}{\alpha - \alpha}} \frac{\sin\left(1 + \frac{\pi}{\alpha - \pi}\right)\theta}{1 - \frac{\pi}{\alpha - \pi}} + \frac{q\psi}{2\tau^{1/2} (1 - \tau)^{\beta}} \frac{\sin\left(1 + \frac{\pi}{\alpha - \pi}\right)\theta}{1 + \frac{\pi}{\alpha - \pi}}$$

where x_0 and y_0 are integration constants.

The above transformation relations are conformal as long as the streamline is not tangent to a characteristic, where the Jacobian $\partial(x,y)/\partial(q,\theta)$ equals zero. The locus of the points of tangency of the characteristics and the streamlines is called the limiting line by Tollmien (reference 16) and Tsien (reference 17). Its position in the hodograph plane is governed by the following equation:

$$\frac{\partial \psi}{\partial \theta} = \pm 2\tau \sqrt{\frac{1-\tau}{(2\beta+1)\tau-1}} \frac{\partial \psi}{\partial \tau}$$
 (25)

Substituting ψ into equation (17) results in a relation of θ and q which represents the limiting line. Here

$$\cot\left(\frac{\pi}{\pi-\alpha}\theta\right) = \pm \frac{2(\pi-\alpha)}{\pi} \sqrt{\frac{1-\tau}{(2\beta+1)\tau-1}} \frac{F^*(a,b;c;\tau)}{F(a,b;c;\tau)}$$
(26)

where

$$F^{*}(a,b; c; \tau) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)\Gamma(b+k)}{\Gamma(c+k)\Gamma(k+1)} \left[\frac{\pi}{2(\pi-\alpha)} + k \right] \tau^{k}$$
(27)

With the knowledge of the position of the limiting line in the hodograph and the respective values of $\psi(q,\theta)$ for points upon it, the corresponding limiting line in the physical plane can be found by means of equation (24).

Examples of Generalized Ringleb Flow

It may be of interest to both the theoretical and the practical aerodynamicist to show a few concrete examples of compressible flows derived from the incompressible flow turning around convex corners of different angles. Compressible flows about corners of 46.8°, 90°, 132.9°, and 150.8° are shown. This seemingly arbitrary choice of angles is due to the fact that the corresponding hypergeometric functions have a finite number of terms in the series expansion.

Compressible flow turning about a smooth corner of a 90° angle.-Figure 3(a) shows the incompressible flow about a convex corner of 90° both in the physical plane and in the hodograph plane. (Actually the

physical plane has been rotated 45° to emphasize the symmetry of the flow.) The velocity at \overline{B} is infinite so there is an infinite region in the hodograph plane. The hodograph streamlines are one branch of a family of four-leaved lemniscates, all tangent at the origin where the quadrupole singularity is located. It is easy to see that the physical flow at infinity maps to the neighborhood of the hodograph origin $\overline{A}, \overline{C}$ where the velocity is zero. Figure 3(b) shows the corresponding compressible flow in both the physical and hodograph planes. This is obtained by Chaplygin's method; for example, take a streamline of incompressible flow, say $\psi = C_1$, and change the velocity magnitude from

$$\left(\frac{\pi}{\alpha q}\right)^{\frac{\pi}{\alpha-\pi}}$$
 to $\left(\frac{\pi}{\alpha q}\right)^{\frac{\pi}{\alpha-\pi}}$ $F\left(a,b;c;\frac{q^2}{q_m^2}\right)$ without changing the phase angle θ

of the velocity. This can be done graphically in the hodograph plane. A few features should be noted. The compressible domain is confined within a circle of radius q_{m} . The sonic circle divides the hodograph region into two parts, that is, subsonic or elliptic domain (q < a)and supersonic or hyperbolic domain (q > a). Within the subsonic domain the two planes are conformally related. For the supersonic domain, the two planes are still conformally related up to that streamline, say $\psi = C_0^+$, which is tangent to a characteristic at A. The corresponding physical streamline (called streamline b later) has a discontinuity in slope at A. To examine this flow in more detail, figure 4(a) shows that compressible flow is physically possible for streamline b and for all streamlines outside it. On streamline b, the slope is discontinuous at A and $C(q/a_0 = 1.12)$ which corresponds to the infinite slope of q or infinite acceleration at these points as shown in figure 4(b) and to the points of tangency of the streamline to a characteristic as shown in figure 4(c). It is interesting to find that the maximum obtainable velocity for smooth transonic flow can be found at B where $q/a_0 = 1.33$ which is smaller than that of Ringleb flow $(q/a_0 = 1.67)$ which is given in reference 7. The limiting lines are shown in both the physical and hodograph planes. The points A and C are the cusps of the limiting lines in the physical planes. The streamlines inside b double back from the limiting line, which is the locus of the streamline cusps. This discussion parallels the work of Ringleb (reference 12) and Von Karmán (reference 7).

However, there are a number of interesting new features to be explored for this case. First, in figure 4(a) the sonic line in the physical plane is always perpendicular to the convex corner symmetrically at D and E. (The dotted corner represents the incompressible boundary; the solid lines, the compressible.) The loop of the sonic line is somewhat of the shape of one branch of a lemniscate, in contrast with

the circle in the Ringleb case. The limiting line is also symmetrical and terminates at D and E, normal to the corner. The two inner branches AD and CE of the limiting line lie just inside the sonic line in the physical plane. In the hodograph plane, they are also normal to the boundary and tangent to the sonic circle. However, the b streamline with maximum velocity $q/a_0 = 1.33$ begins to be tangent to characteristics at A and C where this streamline has infinite acceleration. Although the limiting line is a smooth symmetrical curve in the hodograph plane, the Jacobian $\partial(x,y)/\partial(q,\theta) = 0$ at A and C and the conformal mapping to the physical plane breaks down. The limiting line in the physical plane has cusps at A and C. Now the hodograph region, a quadrant of the circle of ultimate velocity, is divided into four kinds of regions by the limiting line DACE and the streamline OABCO. (See fig. 4(c).) The region OABC represents a physical field of smooth isentropic flow freely turning the corner. The piece of flow within ODA is also isentropic physical flow, but this flow cannot continue beyond the limiting lines AD or CE unless fluid is properly withdrawn along AD and injected along CE. For example, in figure 4(a) streamline c is first reflected at an oblique angle by the branch of the limiting line AD. The reflected portion corresponds to the portion of the streamline c beyond the limiting line in the hodograph. Then the limiting line reflects c again at another oblique angle. This portion of c lies in the region between the limiting line and the streamline OABCO in the hodograph. Then the streamline c proceeds, doubling back at the limiting line and creating a symmetrical pattern with respect to the center line of the corner. It is interesting to see that the entire hodograph flow in the quadrant of the ultimatevelocity circle maps into a three-sheeted Riemann surface in the physical plane. If a vertical cut of the flow field through D and E is made. one can imagine a threefold sheet as shown in figure 4(d). The branches of the limiting line can be visualized as folding lines of the Riemann surface and each point on c lying between branches of the limiting line has a triple-valued velocity as shown in figure 4(b). This conception may help to explain the mathematical nature of the flow. However, the second and third sheets of the Riemann surface have no physical reality, and only the first sheet corresponds to physically possible flow.

Finally, in the Ringleb flow, the limiting line in the hodograph is monotonic, increasing in curvature up to \mathbf{q}_{m} , and tangent to both the sonic circle (this can be extended in figure 22 of reference 7) and to the ultimate-velocity circle. It resembles a half ellipse. In the case of a 90° corner, the limiting line has two points of inflection although still tangent to both the sonic and the ultimate-velocity circles.

Compressible flow turning about other angles. The flow turning a 90° angle was described fully in order to show its physical and mathematical features. Three more corner angles, namely 46.8°, 132.9°,

and 150.8°, have been calculated and are shown in figures 5 to 7. The notations are consistent with the case of the 90° corner. The acute angle of 46.8° is between the Ringleb case (0° angle) and the 90° angle. Not many new features can be shown in figures 5(a) to 5(e) except that $\left(\frac{q}{a_0}\right)_{max} = 1.50$ at B. A detailed study of these figures can show many features of the Ringleb case which, unfortunately, has not been fully illustrated except in reference 7. Incidentally, the case of Kraft and Dibble (reference 13) has an acute angle of 60° which lies between 0° and 90° . The value of $\left(\frac{q}{a_0}\right)_{max}$ for smooth flow is hard to estimate from their curves. However, it appears to lie between the present values for 46.8° and 90° .

Figures 6(a) to 6(d) show a corner of 132.9° . This case shows additional interesting features. For instance, at F (fig. 6(c)) there is a turning point on the limiting line as it reflects from the straight boundary in the hodograph. For this value of q/a_{\circ} , $\psi=0$ and thus the circular arc GF is also part of the compressible boundary. In the physical plane this section of the boundary is a circular arc where q/a_{\circ} is constant (1.00). Although the bounding streamline appears smooth, the enlarged view in figure 6(d) shows that it is not. For the last smooth streamline b, q/a_{\circ} is practically constant along that portion of the streamline ABC which is nearly a circular arc. The legs of this streamline are nearly straight lines forming an angle of 139° . The value of q/a_{\circ} at B is 0.98.

The limiting line will form a loop at velocities higher than $\left(q/a_0\right)_F$ and is tangent to the ultimate-velocity circle. Thus the limiting line, the streamline b, and the constant-velocity arc GF will divide the sector of the ultimate-velocity circle into six kinds of regions. Then the flow in the physical plane will give a five-sheeted Riemann surface rather than three as before.

The projection of the extended straight-sided boundaries into the field of physical flow and the existence of a rounded constant-velocity tip show this case is essentially different from the preceding angles where the flow is closely related to the Ringleb flow.

Figures 7(a) and 7(b) show the flow about a corner angle of 150.8°. Calculated data are insufficient to predict the shape of the sonic line near D and E. This is the most reasonable guess for the shape. The looped shape of the sonic line is very long and narrow. It is perpendicular to the extended boundaries of the corner angle at D and E. The inner branches of the limiting line coincide with the sonic line near the corner. There are many questions about this flow which have

not been settled by the authors. These unsettled data are published purely for stimulation of future investigation.

If this apparent pattern of the sonic loop is extended to the convex corner angle very near but smaller than 180° , it is expected that the loop will become very tall and narrow. In the limit $2\pi - \alpha \longrightarrow 180^{\circ}$, the sonic loop probably collapses into a single straight line perpendicular to the wall, extending to infinity.

When the calculation was undertaken, the authors anticipated finding the relation of the corner angle and maximum q/a_0 in isentropic flow. However, with the few angles studied, $\left(q/a_0\right)_{max}$ does not follow any simple curve, which is all that can be concluded at this time. It seems significant that the maximum velocity point does not shift off the corner center line, and the flow remains symmetrical.

It is apparent that even the simple corner flow deserves more extensive study. It is expected that this simple flow will help in understanding more of compressible flow and its nonlinear equations.

COMPRESSIBLE FLOW THROUGH A TWO-DIMENSIONAL

SYMMETRICAL CONTRACTING CHANNEL

The usual requirements for an incompressible flow through a two-dimensional contracting channel are a low, uniform incoming flow velocity and a high, uniform outgoing velocity at the throat. Uniform velocity at the throat cannot be achieved by imposing arbitrary outer boundaries to the channel. However, fortunately, in the hodograph plane, only a source and sink need be specified for such a flow. As far as the corresponding boundary streamlines are concerned, the choice is left entirely to the aerodynamic designer of the channel; he is at liberty to choose those hodograph boundary streamlines which are easy to express analytically. Thus the whole class of incompressible channel flows can be treated favorably by the hodograph method. Along this line of thought, Whitehead, Wu, and Waters (reference 15) show the details of calculating such a symmetrical channel for incompressible flow. However, the method can be applied also to the unsymmetrical channel, if some analytic expression can be found for the channel boundaries.

²Incidentally, the present authors have found a misstatement in equation (9) in reference 15. The last two terms of equation (9) do not cancel as indicated for the case k=2.

The aim of the present report is to show the extension of this hodograph method to calculate compressible flows through such contracting channels. This is achieved by first expressing the incompressible case in a power series of q and then finding the corresponding compressible flow.

Incompressible Flow through a Channel

The most practical case to consider is the flow through a two-dimensional symmetrical channel. For simplicity in analysis, take the ratio of incoming to outgoing velocity as 1:2 for the incompressible flow. Since the flow is symmetrical with respect to the horizontal axis, only the upper half of the channel is considered. The corresponding boundary streamline in the hodograph is the vertical radius and the 90° arc of a unit circle whose center is the source located at \mathbf{q}_1 . A sink is located at the end of this arc, namely $\mathbf{q}_{2i} = 2\mathbf{q}_1$. The other boundary is the image with respect to the horizontal axis. There are two advantages of this choice. First, the whole flow lies in the annular region between the two arcs of radius \mathbf{q}_1 and \mathbf{q}_2 , so that one series can represent the entire flow without the complication of analytic continuation. Second, the incompressible flow can be described in a simple analytic expression in the hodograph plane. Even in this simple case, the computation is quite involved.

There is an inherent disadvantage with this choice; that is, the length of the channel will be infinitely long. The practical application of such a channel seems lost. However, if a reasonable engineering tolerance is admitted to the values of the incoming and outgoing velocities, say 1 percent, the channel length will be finite. With the knowledge of this case, a compressible flow for a finite-length channel can be constructed with the technique of analytic continuation.

Following reference 15, it is not difficult to show that the non-dimensional complex potential for the channel incompressible flow with \mathbf{q}_1 = 1 and \mathbf{q}_{2i} = $2\mathbf{q}_1$ can be expressed in the hodograph plane as

$$w_{i} = \frac{\mu}{\pi} \log_{e} \frac{\overline{q}_{i} - 1}{(\overline{q}_{i} - 1)^{2} - 1}$$

$$= \frac{\mu}{\pi} \left[\log_{e} (\overline{q}_{i} - 1) - \log_{e} \overline{q}_{i} - \log_{e} (1 - \frac{\overline{q}_{i}}{2}) - \log_{e} (-2) \right]$$
 (28)

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where $\overline{q}_i = q_i e^{-i\theta} = u_i - iv_i$ is the conjugate velocity vector. Since the complex potential is subject to the indeterminancy of a constant, the term \log_e (-2) can be neglected. The second expression is written to show that the hodograph source is $\log_e\left(\overline{q}_i - 1\right)$ and two hodograph sinks

are $-\log_e \overline{q}_1$ and $-\log_e \left(1 - \frac{\overline{q}_1}{2}\right)$. All are of the same strength. Of

course there is another source of equal strength located at infinity so that the entire flow is steady and in equilibrium. Equation (28) represents the flow field covering the entire hodograph plane. However, if the condition 1 < q < 2 is imposed, equation (28) can be expanded into a single power series of \overline{q}_{1} . Consequently,

$$w_{\underline{1}} = -\frac{1}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} (\overline{q}_{\underline{1}}^{-n} - 2^{-n} \overline{q}_{\underline{1}}^{n})$$
 (29)

If \overline{q}_{i} is expressed explicitly in terms of q_{i} and θ ,

$$w_{i} = -\frac{1}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} \left(q_{i}^{-n} e^{in\theta} - 2^{-n} q_{i}^{n} e^{-in\theta} \right)$$
 (30)

Compressible Flow through a Channel

Now the compressibility effect can be considered. Chaplygin's procedure shows that, for each value of n, the incompressible velocity $\mathbf{q}_1^{\pm n}$ in the stream function will change to a new velocity magnitude $\psi_{\pm n}(\tau)/\psi_{\pm n}(\tau_1)$ while the angularity θ remains the same.³ Being linear in the hodograph plane, all the solutions are superposable. Thus the nondimensional stream function is

$$\psi_{c} = -\frac{1}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} \left[\frac{\psi_{-n}(\tau)}{\psi_{-n}(\tau_{1})} + 2^{-n} \frac{\psi_{n}(\tau)}{\psi_{n}(\tau_{1})} \right] \sin n\theta$$
 (31)

³If $q_{12} = 1$ is chosen, $\psi_{\pm n}(\tau)/\psi_{\pm n}(\tau_2)$ should be used to replace $\psi_{\pm n}(\tau)/\psi_{\pm n}(\tau_1)$ and τ_1 should be replaced everywhere in the later expressions.

Of course, the above $\,\psi_{_{\hbox{\scriptsize c}}}\,\,$ can be considered as the imaginary part of the complex function

$$w_{c} = -\frac{\mu}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} \left[\frac{\psi_{-n}(\tau)}{\psi_{-n}(\tau_{1})} e^{in\theta} - 2 \frac{-n\psi_{n}(\tau)}{\psi_{n}(\tau_{1})} \right] \sin n\theta$$
 (32)

but the real part of \mathbf{w}_c is no longer a solution of the potential ϕ_c as in the case of incompressible flow. It is well-known that ϕ_c and ψ_c are not conjugate functions in compressible flow. It should be remarked than an infinite number of channel shapes of compressible flow can be constructed from the same incompressible flow by choosing some function $\mathbf{f}_{2n}(\tau_1)$ to replace $\psi_{\pm n}(\tau_1)$ so that $\mathbf{f}_{\pm n}(\tau_1) \longrightarrow \mathbf{q}_1^{\pm n}$ as $M \longrightarrow 0$.

Physical Coordinates

As shown in references 4 and 14, introduce the physical coordinate $Z = X_n + iY_n$ to correspond to each eigenvalue n. Then

$$Z = \sum_{n=1}^{\infty} (Z_n - Z_{on}) \qquad (Z_{on}'s \text{ are constants}) \qquad (33)$$

It can be shown that for $n \neq 1$

$$Z_{n} = X_{n} + iY_{n}$$

$$= \frac{\frac{1}{4}}{\pi} \frac{1}{n\tau^{1/2}(1-\tau)^{\beta}} \left\{ \frac{e^{(1-n)i\theta}}{(1-n)\psi_{-n}(\tau_{1})} \left[-\frac{n}{2} \psi_{-n}(\tau) - \tau \psi_{-n'}(\tau) \right] + \frac{2^{-n}e^{(1+n)i\theta}}{(1+n)\psi_{n}(\tau_{1})} \left[\frac{n}{2} \psi_{n}(\tau) - \tau \psi_{n'}(\tau) \right] + \frac{e^{(1+n)i\theta}}{(1+n)\psi_{-n}(\tau_{1})} \left[-\frac{n}{2} \psi_{-n}(\tau) + \tau \psi_{-n'}(\tau) \right] - \frac{2^{-n}e^{-(1-n)i\theta}}{(1-n)\psi_{n}(\tau_{1})} \left[\frac{n}{2} \psi_{n}(\tau) + \tau \psi_{n'}(\tau) \right] \right\}$$

$$(34)$$

where

$$\psi_{\pm n}'(\tau) = \frac{d}{d\tau} \left[\psi_{\pm n}(\tau) \right]$$

For n = 1

$$Z_1 = X_1 + iY_1$$

$$= \frac{1}{\pi} \left\{ \frac{1}{\psi_{1}(\tau_{1})} \left[1 - \frac{1 - (1 - \tau)^{\beta+1}}{(\beta+1)\tau(1-\tau)^{\beta}} \right] - \frac{1}{\tau\psi_{-1}(\tau_{1})} \left[\frac{3\beta+2}{\beta+1} \frac{1}{(1-\tau)^{\beta}} - \frac{\beta}{\beta+1} (1+\beta\tau) \right] \right\} e^{i2\theta} + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{-1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e} (\tau e^{-2i\theta}) + \frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} + \frac{\beta}{\psi_{1}(\tau_{1})} \right] \log_{e}$$

$$\frac{1}{\pi} \left[\frac{1}{\psi_{1}(\tau_{1})} - \frac{1}{\psi_{-1}(\tau)} (3\beta + 2) \right] \frac{(2\beta + 1)}{(\beta + 1)} \left[\frac{1}{(1 - \tau)^{\beta}} - 1 \right] -$$

$$\frac{1}{\pi} \left[\frac{2\beta}{\psi_{1}(\tau_{1})(\beta+1)} - \frac{2\beta(3\beta+2)}{\psi_{-1}(\tau_{1})(\beta+1)} \right] g(\tau) - \frac{2\beta}{\pi\psi_{-1}(\tau_{1})} \log_{e} \tau$$

(35)

where

$$\psi_{1}(\tau) = \frac{\tau^{-1/2}}{\beta + 1} \left[1 - (1 - \tau)^{\beta + 1} \right]$$

$$\psi_{-1}(\tau) = \tau^{-1/2} + \frac{\beta}{2} \psi_{1}(\tau)$$

$$g(\tau) = \frac{1}{2} \int_0^{\tau} \left[\frac{1 - (2\beta + 1)\tau}{(1 - \tau)^{\beta + 1}} - 1 \right] \frac{d\tau}{\tau}$$

Values of the function $g(\tau)$ are shown in table 5 of reference 14.

Numerical Calculation of Compressible Channel Flow

A numerical calculation for the above analysis was made for the case $\tau_1 = 0.02 \, (M_1 = 0.320, q_1 = 354.0 \, \text{ft/sec}, \text{ and } a_0 = 1117.4 \, \text{ft/sec}).$ For comparison, the incompressible channel flow with the same inlet velocity was also made. The hodograph boundary and the channel geometry for both flows are shown in figures 8(a) and 8(b). For both cases, the hodograph source is located at A $(q_1 = 354.0 \text{ ft/sec})$. The incompressible hodograph sink is $B_i(q_{2i} = 2q_1)$. The streamline boundary $\psi = 2$ is chosen for both the compressible and incompressible cases. Note that, for the same q_1 , q_{2c} is much larger than $2q_1$. (In fact, $M_2 = 0.787$ and $q_{2c} = 825$ ft/sec.) A few points in figures 8(a) and 8(b) need some clarification. Far upstream, both channels have the same width 4, and $\psi_1 = \psi_c = 2$ on the upper boundaries because both channels have identical inlet conditions. The points of inflection of the incompressible and compressible channel boundary are I_i and I_c , respectively. As expected from the compressibility effect, the compressible flow channel is wider than the incompressible one. However, if outlet conditions of both channels were matched $(q_{2c} = q_{2i})$, the incompressible channel would be wider than the compressible one.

The convergence of the series solution in $\psi_{C'}$ is extremely slow. It is difficult to obtain a reasonably good summation with n up to 15 as given in reference 9, particularly when the velocity phase angle is very small and the Mach number is nearly sonic. Shanks' method

(reference 10) makes possible a closer approximation to the value of $\psi_{\rm C}$ with so few terms. It had been planned to calculate the compressible channel flow with sonic throat velocity. However, owing to the insufficient data in the table and slow convergence of the series, this project was not carried through although the authors fully realize the engineering importance of a contracting channel with sonic throat. The example given shows it is possible to obtain an exact solution for compressible channel flow and that this method can be applied to the sonic case when sufficient data are available.

Figure 9 shows the various streamlines in the $\tau\theta$ -plane. The maximum τ at the throat is 0.11 (M = 0.787). Owing to the slow convergence of the infinite series of $\psi_{\rm C}$, $\tau_{\rm max}$ at the channel throat is only reasonably correct and may be subject to a small error. It is noticed that the maximum velocity angle θ of each streamline occurs nearly at the same value, τ = 0.042, where the points of inflection are located.

Figures 10(a) and 10(b) show the position of the boundary streamlines of both the compressible and incompressible cases expressed in terms of $x=x(\tau)$ and $y=y(\tau)$. In the compressible case, $\tau=q_e^2/q_m^2$ is already defined. For the incompressible case, τ is directly proportional to the square of the incompressible flow velocity where the

constant of proportionality is taken as $\frac{1}{(\gamma-1)a_0^2} = \frac{1}{q_m^2}$ so that $(\gamma-1)a_0^2 = \frac{1}{q_m^2}$. Then τ is a good measure of relative velocity magnitudes in the compressible and incompressible flows. It is difficult to calculate both $x(\tau)$ and $y(\tau)$ in the compressible flow. The dashed line of ψ_c means the best approximation so far. Similarly the x-coordinates of the center streamlines $\psi_1 = 0$ and $\psi_c = 0$ as a function of τ are also plotted in figure 11. With the data along the streamlines $\psi_c = 0$, 1, and 2 the approximate contour lines of constant velocity for the compressible flow channel near the point of inflection I_c can be shown (fig. 12). To compare details of the channel wall, the boundary line of the incompressible flow is translated so that its point of inflec-

tion I_1 coincides with I_c (fig. 13). It shows that the channel area of the compressible case decreases slower with x than the incompress-

ible one in the neighborhood of the point of inflection.

The Johns Hopkins University
Baltimore, Md., May 28, 1952

APPENDIX A

EXTENSION OF HUCKEL'S TABLES FOR SUBSONIC RANGE

For the contracting channel, the whole flow region covers only a small range of τ . Many values of the Chaplygin function for τ intermediate to the arguments given in Huckel's tables (reference 9) are needed to determine the flow field accurately. In order to avoid interpolating every time, each subsonic section of the tables was interpolated as a unit so the Chaplygin functions can be read directly as needed. These values are given in tables 1 to 4. The accuracy of the values should be at worst only one place less than the figures in the original tables.

As has been noted in the errata, the headings $dY_k/d\tau$ and $dY_{-k}/d\tau$ for tables 3 and 4 of Huckel's report are in error. To obtain the actual derivative, each tabulated value should be multiplied by $-k\beta/2$. The values here listed in table 3 and table 4 are the derivatives and are denoted $Y_k'(\tau)$ and $Y_{-k}'(\tau)$ to prevent confusion with the headings in the original tables. Otherwise the arrangement and notation correspond exactly to Huckel's tables.

APPENDIX B

SYMBOLS

a	sound velocity $\left(\sqrt{\frac{\gamma p}{\rho}} = \sqrt{\gamma RT}\right)$
a _o	stagnation sound velocity $\left(\sqrt{\frac{\gamma P_O}{\rho_O}} = \sqrt{\gamma R T_O}\right)$
a	typical smooth streamline
Ъ	streamline of smooth isentropic flow with maximum velocity
С	typical streamline that doubles back at limiting lines
k	index number for summation
m	index power
n	eigenvalue
p	local pressure
P_{O}	stagnation pressure
q	velocity magnitude
$\mathtt{q}_\mathtt{i}$	velocity magnitude of incompressible flow
$q_{f c}$	velocity magnitude of compressible flow
<u>q</u> i	incompressible conjugate velocity vector $\left(\frac{dw_{i}}{dz} = u_{i} - iv_{i}\right)$
$ar{d}^{ extbf{m}}$	ultimate velocity $\left(a_0\sqrt{\frac{2}{\gamma-1}}\right)$
$\mathfrak{q}_{\mathtt{l}}$	inlet velocity

q_2	throat velocity
iS ^p	incompressible throat velocity
q _{2c}	compressible throat velocity
u,v	velocity components
u _i ,v _i	incompressible velocity components
w _i	complex potential
w _c	complex variable function, the imaginary part of which is the stream function
x,y	rectangular coordinates
z	complex variable (re ^{i@})
A,C	locations of cusps of limiting line
В .	location of maximum velocity in smooth isentropic flow
D,E	termination of sonic line and limiting line at convex corner
F,G	intersections of limiting line with convex corner
$F\left(a,b; c; \frac{q^2}{q_m^2}\right)$	hypergeometric function .
Ii	point of inflection of channel boundary for incompressible flow
I_e	point of inflection of channel boundary for compressible flow
M	Mach number
R	molar gas constant

T temperature

 $T_{\rm O}$ stagnation temperature

 $\mathbf{X_n}, \mathbf{Y_n}$ physical coordinate corresponding to each eigenvalue n

 $Z_n = X_n + iY_n$

Z physical coordinates corresponding to a hodograph

point

angle covered by flow

 $2\pi - \alpha$ angle of convex corner

 $\beta = \frac{1}{\gamma - 1}$

 γ specific heat ratio; for air $\gamma = 1.4$

heta velocity phase angle

 θ_1 phase angle of incompressible velocity

 θ_c phase angle of compressible velocity

ρ local density

 ρ_{O} stagnation density

 $\tau = \frac{q^2}{q_m^2} = \frac{2}{\gamma - 1} \frac{q^2}{a_0^2}$

 $\phi_{\mathtt{i}}$ potential in incompressible flow

 $\phi_{
m c}$ potential in compressible flow

ψ stream function

 $\psi_{\mathbf{i}}$ incompressible stream function

 $\psi_{\mathbf{c}}$ compressible stream function

$$\psi_{\pm n}(q) = q^{\pm n} F(a_n, b_n; c_n; \tau)$$

 Θ phase angle of complex variable

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iΝ

TABLE 1.- $Y_k(\tau)$ FOR VARIOUS VALUES OF k

т	Y ₁	Y2	Y ₃	Yh	Y ₅	^ч 6	T ^Y	Y ₈
0.02	0.97525	0.95087	0.92700	0.90369	0.88093	0.85873	0.83708	0.81596
.022	.97280	.94606	.91991	.89446	.86966	.84553	.82207	179923
.024	.97036	.94126	.91287	.88530	.85850	83250	.80728	.78278
.026	.96792	•936 1 8	.90587	.87621	.84745	.81963	•79270	.76661
.028	96549	-93171	.89891	.86718	.83651	.80691	-77833	.75072
.03	.96306	.92695	.89198	.85822	.82568	.79434	.76416	.73511
.032 .034	.96064 .95822	•92221 01710	.88509 .87824	.84934	-81.496	.78193	.75021	-71977
.036	.95581	.91749 .91279	.87143	.84053 .83179	.80435 .79385	.76969 .75760	.73647 .72294	.70470 .68989
.038	.95340	.90811	.86466	.82311	.78345	.74566	70062	.67534
.04	.95099	.90346	.85792	.81,449	.77316	.73386	.70962 .69651	66104
.042	94859	89882	.851.22	·80594	.76298	.72221	.68359	.64699
.044	94619	.89419	.84456	.79746	.75290	.71071	. •67086	.63319
.046	-94380	.88958	.83794	.78905	.74292	.69936	.65832	.61964
.048 .05	.94142 .93905	.88498 .88039	.83136 .82481	.78072 .77245	.73304	.68816	.64598	.60634
.052	.93668	.87582	.81830	.76424	.72326 .71358	.67710 .66618	.63383 .62187	.59328 .58045
.054	.93431	.87127	.81183	.75609	.70400	.65540	.61009	.56785
.056	.93195	.86674	.80539	.74801	.69452	.64476	.59849	.55547
.058	.92959	.86223	.79899	.74000	.6851.5	.63426	.58706	.54331
.06	.92723	.85773	.79262	.73205	.67588	.62389	.57581	.53138
.062 .064	.92488 .92254	.85325 .84878	.78629	.72416 .71634	.66671	.61366	.56474	.51.967
.066	.92234	.84433	.78000 .77375	.70858	.65763 .64864	.60356 .59359	.55384 .5 4 311	.50817 .49688
.068	.91787	.83990	.76753	.70088	.63974	.58375	.53256	.48580
.07	91554	.83549	.76135	.69325	.63094	.57405	.52218	.47492
.072	.91322	.83109	.75520	.68568	.62223	.56448	.51196	.46424
.074	.91090	.82671	.74909	.67817	.61362	.55503	.50190	.45376
.076 .078	.90858 .90627	.82234 .81799	.74302 .73698	.67072 .66333	.60510 .59667	.54570 .53650	.49200 .48226	.44348
.08010	.90396	.81366	.73098	.65600	.58834	.53650 .52742	.40226 .47268	.43340 .42352
.082	.90166	.80934	.72501	.64873	.58010	.51847	.46325	.41383
.084	.89936	. 80504	.71901	.64152	.571.95	.5096¥	.45397	.40432
.086	.89707	.80076	.71317	.63437	.56388	50093	44484	.39498
.088	.89479 .89251	.79649 .79224	.70731 .70149	.62729 .62027	.55589 .54798	.49233 .48384	.43586 .42704	.38580
.092	.89023	.78800	.69570	.61331	.54016	.40304 .47547	.42704	.37679 .36796
.094	.88796	.78378	68994	.60640	.53243	46722	.40982	.35931
.096	.88569	.77958	.68421	.59954	.52479	.45909	.40142	.35083
.098	.88343	.77539	.67852	.59274	.51724	.45107	.39316	.34253
.10	.88117 .87892	.77122 .76706	.67286 .66724	.58600	.50979 .50241	.44315	.38503	-33439 -32641
104	.87667	.76292	.66165	.57932 .57270	.49510	.43534 .42765	•37704 •36919	.31858
.106	.87443	.75880	.65609	.56613	.48787	42007	.36147	.31090
.108	.87219	.75469	.65057	.55962	.48073	.41259	.35388	-30337
1 .11	.86996	.75060	.64508	.55316	47367	.40521	.34641	.29599
.112	.86773 .86551	.74652	.63963	.54676	.46669	-39794	-33907	.28875
114	.86329	.74246 .73841	.63421 .62882	.54041 .53412	.45979 .45297	.39077 .38371	.33186 .32477	.28167 .27473
1 318	.86107	.73438	.62346	.52789	.44622	.37674	.31781	.26793
12]	.85886	.73037	.61813	.52171	.43955	.36987	.31097	.26127
.122	.85665	.72637	.61283	.51.558	.43296	.36310	.30425	.25475
.124 .126	.85445 .85226	.72238	.60757	.50951.	.42645	.35643	.29764	.24836
.128	.85007	.71841 .71446	.60235 .59716	.503 4 9 .49752	.42001 .41364	.34985 -34337	.29114 .28476	.24210 .23596
.13	.84789	.71.053	.59201	.49160	.40733	•3 4 337 •33699	.27849	.23596
.132	.84571	.70661	.58689	.48573	.40110	.33070	.27233	.22407
.134	.84353	.70270	.58180	.47991	301-05	.32450	.26628	.21831
136	.84136	.69881	.57674	.47415	.38887	.31839	.26034	.21267
.138	.83919 .83703	.69493 .69107	.57170 .56668	.46845 .46280	.38287 .37695	.31237 .30645	.25451 .24879	.20715
.142	.83487	.68722	.56170	.46260 .45720	.37110	.30045 .30062	.24079	.19648
.144	.83272	.68339	.55676	.45164	.36531	.29487	.23765	.19131
.146	.83057	.67958	.55186	.44613	.35958	.28920	.23222	.18625
148	.82843	.67578	.54699	.44067	.35391	.28362	.22689	.18129
.15	.82629 .82416	.67200 .66823	.5421.5 .53734	.43526 .42990	.34832 .34280	.27811 .27269	.22166 .21652	.17644 .17170
.154	.82203	.66447	.53256	.42459	.33735	.26736	.21148	.16706
.156	.81991	.66073	.52781	.41933	.33196	.26211	.20654	.16252
.158	.81779	.65701	.52308	.41412	.32664	.25694	.20169	.15808
.16	.81567 .81356	.65331 .64962	.51838	.40896	.32138	.25185	.19694	.15375
.164	.81145	.64594	.51372 .50909	.40384 .39877	.31619 .31106	.24684 .24191	.19228 .18770	.14951 .14536
166	.80935	.64227	.50449	•39375	.30599	.23705	.18320	.14130
<u> </u>						J		

TABLE 1.- $\mathbf{Y}_{\mathbf{k}}(\tau)$ FOR VARIOUS VALUES OF k - Concluded

	-					1	
т	¥ ₉	y ₁₀	, 117	Y ₁₂	Y _{13.}	· Y ₁₄	^Ү 15
0.02	0.79537	0.77530	0.75573	0.73666	0.71806	0.69993	0.68226
.022	•7770 4	.75549	•73 44 7	.71405	69428	.67498	.65627
.024	.75906	.73609	.71372	.69203	.67114	.65076	.53108
.026	.74142	.71709	.69346	.67060	.64863	.62727 .60450	.60669
.028	.72412 .70716	.69849 .68028	.67368 .65438	.64975 .62947	.62675 .60551	.58246	.58309 .56029
.032	.69054	.66249	.63556	.60976	.584.01	.56113	.53829
.034	.67425	.64511	.61722	.59060	.56495	.54051	.51709
.036	.65829	.62814	.59935 .58195	.57196	.54562	.52060	.49668
.038	.64266	.61156	.58195	.55383	.52692	.50139 .48287	.47706
.042	.62736 .61237	.59538 .57957	.56502 .54853	.53619 .51904	.50884 .49129	.46493	.45823 .44001
.044	.59768	.56411	.53245	.50238	.47424	.44755	.42239
.046	.58328	.54898	.51675	.48620	.45768	.43072	.40537
.048	.56915	.53418	.50141	-47049	.44161	.41444	.38895
.05	.55530	.51972	.48642	.45523 .44040	.42604	.39871 .38352	.37313
.052 .054	.54174 .52847	.50560 .49182	.47183 .45764	.42599	.41097 .39638	.36885	.35787 .34317
.056	.51548	.47837	.44385	.41198	.38226	.35469	.32903
.058	.50277	.46524	.43045	39837	.36859	.34102	.31545
.06	.49034	.45244	.41745	.38515	.35534	.32782	.30244
.062 .064	.47816 .46623	.43995 .42774	.40478 .39242	.37231 .35984	.34249 .33003	.31507 .30276	.28987 .27774
.066	.45454	.41580	.38035	• 35-504 • 34774	31796	.29088	.26604
.068	44309	.40413	.36857	33601	.30638	.27941	.25477
.07	-43189	.39272	.35702	.32466	.29516	-26834	.24994
.072	.42093	.38159	.34591	.31364	.28428	.25765	.23351
.074	.41020 .39970	.37074 .36017	.33506 .32453	.30293 .29252	.27374 .26353	.24734 .23740	.22348 .21384
.078	.38944	.34968	.31431	.28241	.25366	.22782	.20459
.08	-37941	.33985	.30439	.27260	.24412	.21860	.19574
.082	.36960	.33006	.29472	.26309	.23489	.20971	.18721
.084	.35999 .35058	.32050 .31116	.28530 .27613	.25387 .24494	.22596 .21733	.20113 .19285	.17899 .17108
.088	.34138	.30205	.26721	.23630	.20900	.18487	.16348
.09	-33238	.29315	.25852	.22795	.20098	.17719	.15620
.092	.32358	.28448	.25008	.21985	.19323	.16979	.14920
.094	.31498 .30657	.27603 .26780	.24188 .23392	.21199 .20436	.18573 .17848	.16267 .15582	.14247 .13601
.096 .098	.29835	.25979	.22620	.19696	.17145	.14921	.12983
.10	.29032	.25201	.21871	.18978	.16465	.14284	.12391
.102	.28247	.24442	.21143	.18283	.15809	.13671	.11822
.104 .106	.27480	.23701	.20435 .19746	.17610 .16959	.15177 .14568	.13081 .12514	.11275 .10750
.108	.26730 .25997	.22978 .22273	.19076	.16331	.13982	.11970	.10248
. <u>11</u>	.25280	.21585	.18426	.15725	.13419	.11449	.09767
.112	.24580	.20915	.17795	.15138	.12874	.10948	.09307
.114 .116	.23896	.20263 .19629	.17183 .16589	.14568 .14016	.12347 .11838	.10465 .10000	.08865 .08441
811.	.23228 .22576	.19029	.16013	.13482	.11347	.09552	.08035
.12	.21940	.18417	.15455	.12965	.10874	.09119	.07646
.122	.21319	.17835	.14913	.12465	.10418	.08704	.07273
.124 .126	.20712 .20119	.17267 .16713	.14387 .13876	.11982 .11516	.09979 .09556	.08307 .07927	.06916 .06575
.128	.19540	.16174	.13381	.11066	.09149	.07563	.06250
.13	.18975	.15649	.12901	.10631	.08759	.07214	.05941
.132	.18424	.15139	.12436	.10211	.08383	.06879	.05645
.134	.17886	.14643 .14161	.11985 .11548	.09805 .09413	.08020 .07670	.06557 .06247	.05361 .05088
.136 .138	.17361 .16849	.13693	.11124	.09034	.07333	.05950	.05066
.14	.16349	.13238	.10714	.08667	.07008	.05665	.04578
.142	.15861	.12796	.10317	.08313	.06696	.05392	.04340
.144	.15385	.12366	.09932	.07972	.06996 .06108	.05131 .04881	.04113 .03897
.146 .148	.14921 .14469	.11948 .11541	.09559 .09198	.07643 .07326	.05832	.04601. .04642	.03692
.15	.14029	.11146	.08849	.07021	.05567	.04413	.03497
.152	.13600	.10762	.08511	.06726	.05312	.04194	.03311
.154	.13182	.10389	.08184	.06441 .06166	.05067 .04831	.03984 .03783	.03133 .02963
.156 .158	.12774 .12376	.10027 .09676	.07867 .07560	.05901	.04605	.03591	.02801
.16	.11987	.09335	.07264	.05647	.04388	.03407	.02645
.162	.11609	.09004	.06978	.05402	.04180	.03231	.02497
.164 .166	.11241 .10882	.08683 .08371	.06701 .06433	.05166 .04938	.03980 .03788	.03063 .02903	.02357
	*10002		••••	•••	,	,	
·					·		77.6

~ NACA_

TABLE 2.- $Y_{-k}(\tau)$ FOR VARIOUS VALUES OF k

				· · ·		 -		
т	Y-1	Y_2	Y3	Т_h	Y_5	¥_6	Y-7	Y_8
0.02	1.02438	1.06098	1.08708	1.11260	1.14016	1.16911	1.19910	1.22999
.022	1.02674	1.06790	1.09735	1.12550	1.15603	1.18835	1.22185	1.25673
.024	1.02909	1.07489	1.10793	1.13885	1.17243	1.20817	1.24537	1.28428
.026	1.03144	1.08196	1.11882	1.15265	1.18936	1.22859	1.26967	1.31269
.028	1.03378 1.03611	1.08911	1.13002	1.16690	1.20683	1.24966	1.29476	1.34201
.032	1.03843	1.09633 1.10362	1.14154 1.15338	1.18160 1.19677	1.22485 1.24342	1.27139	1.32064	1.37229
.034	1.04074	1.11098	1.16554	1.21241	1.26255	1.29377	1.34730 1.37475	1.40354 1.43577
.036	1.04303	1.11841	1.17803	1.22852	1.28224	1.34049	1.40299	1.46899
.038	1.04530	1.12591	1.19085	1.24510	1.30249	1.36486	1.43202	1.50326
.04	1.04755	1.13347	1.20100	1.26215	1.32332	1.38993	1.46184	1.53869
.042 .044	1.04979 1.05202	1.14107 1.14870	1.21746	1.27979	1.34490	1.41950	1.49276	1.57532
.046	1.05425	1.15635	1.23123 1.24531	1.29804 1.31689	1.36728	1.44284	1.52482 1.55812	1.61420
.048	1.05647	1.16402	1.25971	1.33634	1.39049 1.41456	1.47079 1.49978	1.59270	1.65333 1.69396
.05	1.05869	1.17171	1.27443	1.35639	1.43954	1.52984	1.62862	1.73604
.052	1.06089	1.17943	1.28945	1.37706	1.46541	1.56100	1.66594	1.77982
.054	1.06307	1.18717	1.30477	1.39835	1.49218	1.59331	1.70467	1.82540
.056	1.06524	1.19493	1.32138	1.42028	1.51985	1.62685	1.74482	1.87283
.058	1.06740 1.06954	1.20270 1.21049	1.33628	1.44286	1.54842	1.66166	1.78640	1.92251
	1.07167	1.21829	1.35248 1.36896	1.46612 1.49006	1.57789 1.60849	1.69775	1.82943	1.97447
.064	1.07379	1.22608	1.38571	1.51468	1.64027	1.73524 1.77432	1.87427	2.02871 2.08523
.066	1.07590	1.23385	1.40274	1.53999	1.67325	1.81503	1.97037	2.14405
.068	1.07801	1.24161	1.42004	1.56598	1.70745	1.85749	2.02184	2.20517
.07	1.08011	1.24935	1.43760	1.59265	1.74290	1.90171	2.07570	2.26864
.072	1.08219 1.08426	1.25708	1.45541	1.62003	1.77959	1.94773	2.13196	2.33526
.074	1.08632	1.26480 1.27252	1.47346	1.64813	1.81753	1.99557	2.19068	2.40543
.078	1.08837	1.28023	1.49175 1.51028	1.67695 1.70649	1.85672 1.89716	2.04534 2.09707	2.25190 2.31566	2.47930 2.55703
.08	1.09040	1.28793	1.52903	1.73675	1.93888	2.15078	2.38198	2.63886
.082	1.09242	1.29560	1.54799	1.76772	1.98203	2.20669	2.45151	2.72484
.084	1.09443	1.30323	1.56716	1.79940	2.02664	2.26495	2.52450	2.81506
.086 .088	1.09643	1.31082	1.58653	1.83178	2.07273	2.32566	2.60109	2.90958
	1.09842 1.10041	1.31837 1.32588	1.60610 1.62588	1.86486 1.89864	2.12031 2.16941	2.38886 2.45456	2.68141	3.00850
.092	1.10238	1.33336	1.64582	1.93311	2.22002	2.52284	2.76563 2.85376	3.11187 3.22104
.094	1.10434	1.34081	1.66592	1.96827	2.27213	2.59374	2.94577	3.33631
.096	1.10629	1.34822	1.68618	2.00413	2.32574	2.66729	3.04182	3.45783
.098	1.10823	1.35559	1.70660	2.04068	2.38085	2.74351	3.14190	3.58590
.10	1.11015	1.36292	1.72716	2.07790	2.43746	2.82240	3.24609	3.72071
.102	1.11206	1.37020 1.37743	1.74785 1.76866	2.11576 2.15426	2.49566 2.55547	2.90426 2.98917	3.35518	3.86242
106	1.11585	1.38461	1.78959	2.19340	2.61690	3.07718	3.46938 3.58879	4.01129 4.16756
.108	1.11774	1.39174	1.81064	2.23318	2.67997	3.16835	3.71350	4.33157
1 .11	1.11962	1.39882	1.83181	2.27359	2.74469	3.26269	3.84363	4.50372
.112	1.12149	1.40585	1.85306	2.31457	2.81096	3.36020	3.97926	4.68443
.11½ .116	1.12334 1.12518	1.41282 1.41973	1.87438	2.35612	2.87877	3.46088	4.11945	4.87414
1 3118	1.12701	1.42658	1.89577 1.91721	2.39823 2.44091	2.94812 3.01901	3.56473 3.67178	4.26631 4.41902	5.07333
.12	1.12883	1.43336	1.93871	2.48415	3.09145	3.78203	4.57769	5.28267 5.50226
.122	1.13064	1.44008	1.96025	2.52788	3.16542	3.89566	4.74243	5.73220
.124	1.13244	1.44674	1.98182	2.57209	3.24092	4.01269	4.91338	5.97259
.126	1.13423	1.45334	2.00342	2.61677	3.31795	4.13315	5.09067	6.22353
.128 .13	1.13601	1.45988 1.46637	2.02506	2.66193	3.39650	4.25704	5.27448	6.48508
.132	1.13778 1.13954	1.40037	2.04673 2.06839	2.70756 2.75358	3.47657 3.55800	4.38437 4.51503	5.46489 5.66192	6.75730 7.04178
.134	1.14129	1.47914	2.09002	2.79997	3.60479	4.64898	5.86561	7.33871
.136	1.14303	1.48541	2.11162	2.84672	3.72493	4.78619	6.07598	7.64814
.138	1.15576	1.49159	2.13319	2.89383	3.81042	4.92664	6.29305	7.97012
1 .14	1.14648	1.49769	2.15471	2.94130	3.89726	5.07033	6.51684	8.30480
.142 .144	1.14819 1.14989	1.50373 1.50970	2.17618 2.19760	2.98905	3.98528 h 07kb8	5.21723	6.74738	8.65223
.146	1.15158	1.51.560	2.21896	3.03705 3.08529	4.07448 4.16485	5.36732 5.52058	6.98470 7.22884	9.01246 9.38552
.148	1.15326	1.52148	2.24027	3.13375	4.25639	5.67698	7.47988	9.30332
.15	1.15493	1.52718	2.26151	3.18243	4.34908	5.83648	7.73785	10.17028
.152	1.15659	1.53285	2.28264	3.23125	4.44268	5.99888	8.00262	10.58227
.154	1.15824	1.53844	2.30366	3.28019	4.53717	6.16400	8.27371	11.00754
.156 .158	1.15988 1.16151	1.54395 1.54939	2.32456 2.34534	3.32925 3.37842	4.63255 4.72881	6.33179 6.50215	8.55085	11.44613
.16	1.16313	1.55475	2.36601	3.42769	4.72001	6.67493	8.83389 9.12281	11.89795 12.36275
.162	1.16474	1.56003	2.38654	3.47706	4.92364	6.85006	9.12201	12.84008
.164	1.16634	1.56523	2.40692	3.52635	5.02191	7.02747	9.71825	13.32964
.166	1.16793	1.57034	2.42714	3.57553	5.12075	7.20709	10.02475	13.83108
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TABLE 2.- $Y_{-k}(\tau)$ FOR VARIOUS VALUES OF k - Concluded

	,	,	,		Ţ		,
τ	Y_9	Y_10	1-11	Y ₋₁₂	Y ₋₁₃	Y ₋₁₄	Y_15
0.02	1.26173	1.29433	1.32780	1.36215	1.39740	1.43358	1.47069
.022	1.29254	1.32938	1.36725	1.40656	1.44631	1.48790	1.53051
.024	1.32433	1.36562	1.40820	1.45257	1.49742	1.54464	1.59303
.026	1.35717	1.40314	1.45073	1.50035	1.55083	1.60393	1.65845
.028	1.39111	1.44203	1.49492	1.55000	1.60665	1.66592	1.72707
.03	1.42621 1.46251	1.48239	1.54087	1.60171 1.65556	1.66500 1.72590	1.73081 1.79870	1.79925 1.87504
.034	1.50005	1.56755	1.63815	1.71164	1.78938	1.86969	1.95450
.036	1.53885	1.61239	1.68951	1.77005	1.85547	1.94388	2.03772
.038	1.57893	1.65876	1.74275	1.83089	1.92425	2.02147	2.12480
-04	1.62030	1.70668	1.79793	1.89423	1.99580	2.10292	2.21584
.042	1.66317	1.75636	1.85530	1.96028	2.07055	2.18835	2.31150
.044 .046	1.70769	1.80807 1.86206	1.91511	2.02918 2.10108	2.14895 2.23129	2.27790	2.41226 2.51052
.048	1.75396 1.80208	1.91838	1.97760 2.04292	2.17618	2.31780	2.37171 2.47003	2.63068
.05	1.85215	1.97710	2.11119	2.25487	2.40866	2.57318	2.74913
.052	1.90423	2.03825	2.18244	2.33720	2.50391	2.68143	2.87396
.054	1.95838	2.10187	2.25671	2.42324	2.60360	2.79518	3.00527
.056	2.01466	2.16801	2.33404	2.51308	2.70778	2.91488	3.14317
.058	2.07311	2.23671 2.30801	2.41448 2.49811	2.60687 2.70506	2.81652 2.93004	3.04108 3.17438	3.28785 3.43959
.062	2.13375 2.19706	2.38245	2.58554	2.80805	3.04926	3.31493	3.59973
.064	2.26332	2.46052	2.67742	2.91624	3.17508	3.46293	3.76947
.066	2.33293	2.54284	2.77440	3.03003	3.30840	3.61858	3.95001
∴068	2.40612	2.62966	2.87683	3.14994	3.44952	3.78223	4.14215
.07	2.48306	2.72111	2.98490	3.27669	3.59897	3.95453 4.13668	4.34650 4.56329
.072 .074	2.56380 2.64845	2.81742 2.91826	3.09865 3.21816	3.41038 3.55117	3.75686 3.92331	4.32988	4.79276
.076	2.73708	3.02385	3.34351	3.69935	4.09845	4.53533	5.03516
.078	2.82975	3.13424	3.47478	3.85523	4.28249	4.75423	5.29096
.08	2.92651	3.24946	3.61220	4.01938	4.47610	4.98795	5.56117
.082	3.02836	3.37108	3.75702	4.19323	4.68161	5.23689	5.84888
.084 .086	3.13620 3.25074	3.50044 3.63862	3.91154 4.07696	4.37808 4.57533	4.90102 5.13623	5.50145 5.78211	6.15759 6.48930
.088	3.37247	3.78585	4.25398	4.78634	5.38854	6.07977	6.84676
.09 i	3.50151	3.94256	4.44325	5.01237	5.65958	6.39561	7.23250
.092	3.63790	4.10883	4.64479	5.25372	5.94962	6.73313	7.64714
.094	3.78172	4.28475	4.85862	5.51072	6.25906	7.09663	8.09158
.096 .098	3.93303 4.09187	4.47042 4.66595	5.08476 5.32323	5.78372 6.07332	6.58820 6.93844	7.49023 7.91703	8.56682 9.07396
.10	4.25830	4.87150	5.57405	6.38120	7.31014	8.38040	9.61427
.102	4.43508	5.09076	5.84187	6.71070	7.70884	8.88127	10.19878
.104	4.62319	5.32552	6.13119	7.06590	8.14254	9.42059	10.83739
.106	4.82310	5.57698	6.44401	7.45100	8.61424	9.99946	11.53600
.108	5.03533 5.26038	5.84589	6.78133 7.14387	7.86760 8.31833	9.12794 9.68601	10.61918 11.28133	12.30271 13.14450
.112	5.49838	6.13305 6.43861	7.53176	8.80346	10.28948	11.99768	14.06339
.114	5.74949	6.76277	7.94513	9.32329	10.93955	12.78323	15.06158
.116	6.01384	7.10583	8.38415	9.87817	11.63752	13.64888	16.14137
.118	6.29157	7.46827	8.84967	10.46975	12.38489	14.60153	17.30516
.12 .122	6.58282 6.89106	7.85083 8.25760	9.34325 9.87193	11.10378 11.78681	13.18426 14.05003	15.64628 16.78463	18.56319 19.94042
.124	7.21718	8.69158	9.0/193 10.44041	12.52584	14.99560	18.01818	21.46378
.126	7.56168	9.15477	11.05289	13.32487	16.02797	19.34863	23.14824
.128	7.92507	9.64800	11.71096	14.18790	17.15434	20.77808	25.00800
.13	8.30784	10.17177	12.41548	15.11898	18.37894	22.31221	27.06023
.132	8.71012	10.72621	13.16665 13.96467	16.11916 17.18957	19.70334 21.12914	23.98144 25.81577	29.31086 31.76599
.134 .136	9.13204 9.57373	11.31158	14.80979	18.33166	22.65874	27.83710	34.43182
.138	10.03536	12.57622	15.70291	19.54880	24.29334	30.05143	37.31415
.14	10.51724	13.25610	16.65687	20.84427	26.03917	32.46717	40.41914
.142	11.02162	13.97525	17.65183	22.23274	27.91600	35.08651	43.80673
.144 .146	11.54950 12.10178	14.73467 15.53486	18.72179 19.85925	23.72121 25.31368	29.95183 32.15966	37.91165 40.94479	47.53692 51.64171
.148	12.67906	16.37632	21.06551	27.01415	34.54349	44.18893	56.15450
.15	13.28171	17.25956	22.34143	28.82866	37.10348	47.65058	61.08451
.152	13.90826	18.18465	23.68721	30.75737	39.84047	51.41098	66.43272
.154	14.55831	19.15174	25.10315	32.80058	42.75546	55.47628	72.20013
.156 .158	15.23156	20.16105	26.58955 28.14695	34.95859	45.84945 49.12444	59.86098 64.57768	78.38754 84.99595
.16	15.92794 16.64743	21.21293 22.30764	29.77649	37.23170 39.62098	52.58311	69.63353	92.04144
.162	17.39220	23.44645	31.48333	42.13236	56.24378	75.03118	99.65693
,164	18.16212	24.63017	33.27307 .	44.77714	60.12845	80.77293	107.88242
.166	18.95704	25.86010	35.14681	47.56782	64.26012	86.86158	116.73291
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TABLE 3.- $Y_k'(\tau)$ FOR VARIOUS VALUES OF k

								
τ	Y ₁ '	Y2'	^Ұ з'	Y ₄ '	^У 5'	^ч 6'	Y7'	ч ₈ '
0.02	-1.225	-2.413	-3.551	-4.6345	-5.664	-6.640	-7.565	-8. 4 40
.022	-1.222	-2.404	-3.531	-4.599	-5.608	-6.558	-7.454	-8.295
.024	-1.219	-2.396	-3.511	-4.564	-5.552	-6.477	-7.344	-8.152
.026	-1.217	-2.387	-3.493	-4.529	-5.497	-6.397	-7.236	-8.012
.028	-1.215	-2.379	-3.473	-4.494	-5.442	-6.318	-7.129	-7.874
•03	-1.213	-2.370	-3.454	-4.459	-5.387	-6.240	-7.023	-7.738
.032	-1.210	-2.362	-3.435	-4.424	-5.333	-6.162	-6.918	-7.604
.034	-1.207	-2.353	-3.416	- 1 .390	-5.279	-6.085	-6.814	-7.472
.036	-1.204	-2.345	-3.397	-4·356	-5.225	-6.009 -5.934	-6.712	-7.341
.038 .04	-1.202 -1.200	-2.336 -2.328	-3.378	-4.322 -4.288	-5.172 -5.119	-5.93 4 -5.859	-6.611 -6.512	-7.212 -7.084
.042	-1.200	-2.319	-3.359 -3.340	-4.2545	-5.067	-5.785	-6.414	-6.958
.044	-1.194	-2.311	-3.321	4.221	-5.015	~5.712	-6.317	-6.834
.046	-1.192	-2.302	-3.302	-4.1875	-4.964	-5.639	-6.221	-6.712
.048	-1.190	-2.294	-3.283	-4.1545	4.913	-5.567	-6.125	-6.593
.05	-1.188	-2.286	-3.265	-4.1215	-4.862	-5.495	-6.030	-6.476
.052	-1.185	-2.277	-3.246	-4.089	-4.812	-5.424	-5.936	-6.360
.054	-1.182	-2.269	-3.227	-4.0565	-4.762	-5.354	-5.8 11	-6.246
.056	-1.180	-2.260	-3.208	-4.024	-4.712	-5.285	-5.754	-6.133
.058	-1.178	-2.252	-3.190	-3.9915 ·	-4.663	-5.217	-5.665	-6.021
.06	-1.176	-2.244	-3.172	-3.9595	-4.614	-5.150	-5.577	-5.911
.062	-1.173	-2.235	-3.154	-3.9275	-4.566	-5.083	-5.490 -5.404	-5.803 -5.696
.064 .066	-1.170 -1.168	-2.227 -2.218	-3.136	-3.896 -3.8645	-4.518 -4.470	-5.017 -4.951		-5.591
.068	-1.166 -1.166	-2.210	-3.118 -3.100	-3.833	-4.423	1 -4.885	-5.319 -5.235	-5.488
.07	-1.164	-2.203	-3.062	-3.8015	-4.376	-4.820	-5.152	-5.387
.072	-1.161	-2.195	-3.064	-3.7705	-4.329	-4.756	-5.070	-5.287
.074	-1.158	-2.186	-3.046	-3-7395	-4.283	-4.693	-4.990	-5.189
.076	-1.156	-2.178	-3.028	-3.7085	-4.237	-4.631	-4.9 <u>1</u> 0	-5.092
.078	-1.154	-2.170	-3.010	-3.678	-4.191	-4.569	-4.831	-4.996 [
.08	-1.152	-2.162	-2.993	-3.6485	-4.146	-4.508	-4.753	-4.901
.082	-1.149	-2.154	-2.975	-3.6185	-4.101	-4.448	-4.676	-4.807
.084	-1.146	-2.146 -2.138	-2.957	-3.5885 -3.5585	-4.057 -4.013	-4.388	-4.600 -4.525	-4.715 -4.625
.086	-1.143 -1.141	-2.130	-2.940 -2.923	-3.5285	-3.969	-4.329 -4.270	-4.451	-4.537
.09	-1.139	-2.122	-2.906	-3.4995	-3.926	-4.211	-4.378	-4.451
.092	-1.136	-2.114	-2.888	-3.4705	-3.883	-4.153	-4.306	-4.366
.094	-1.133	-2.106	-2.871	-3.4415	-3.840	-4.096	-4.235	-4.282
.096	-1.131	-2.098	-2.854	-3.4125	-3.798	-4.040	-4.165	-4.199
.098	-1.129	-2.090	-2.837	-3.3835	-3.756	-3.984	-4.096	-4.117
10	-1.127	-2.082	-2.820	-3.3545	-3.714	-3.929	-4.028	-4.035
.102	-1.124	-2.074	-2.803	-3.326	-3.673	-3.875	-3.961	-3.955
.104	-1.121	-2.066	-2.787	-3.298	-3.632	-3.821	-3.895	-3.876
.106	-1.119 -1.117	-2.058 -2.050	-2.770	-3.270 -3.242	-3.591 -3.551	-3.768	-3.829 -3.764	-3.799 -3.724
سند.	-1.115	-2.042	-2.753 -2.736	-3.214 -3.214	-3.511	-3.715 -3.662	-3.700	-3.651
.112	-1.112	-2.034	-2.720	-3.1865	-3.471	-3.610	-3.637	-3.579
.114	-1.109	-2.026	-2.703	-3.159	-3.432	-3.559	-3.575	-3.508
.116	-1.107	-2.018	-2.687	-3.1315	-3.393	-3.508	-3.513	-3-437
.118	-1.105	-2.010	-2.670	-3.1045	-3.354	-3.458	-3.452	-3.367
.12	-1.103	-2.003	-2.654	-3.0775	-3.316	-3.409	-3.392	-3.297
.122	-1.100	-1.995	-2.637	-3.051	-3.278	-3.360	-3-333	-3.228
.124	-1.098	-1.987	-2.620	-3.0245	-3.240	-3.312	-3.275	-3.161 -3.006
.126 .128	-1.096	-1.979 -1.971	-2.604 -2.588	-2.998 -2.9715	-3.203 -3.166	-3.264 -3.216	-3.218 -3.161	-3.096 -3.033
.13	-1.094 -1.092	-1.964	-2.572	-2.945	-3.129	-3.269	-3.105	-2.971
.132	-1.089	-1.956	-2.556	-2.919	-3.092	-3.122	-3.050	-2.910
.134	-1.086	-1.948	-2.540	-2.893	-3.056	-3.076	-2.996	-2.849
.136	-1.084	-1.940	-2.524	-2.867	-3.020	-3.031	-2.943	-2.789
.138	-1.082	-1.933	-2.508	-2.8415	-2.984	-2.986	-2.890	-2.730
.14	-1.080	-1.926	-2.493	-2.816	-2.949	-2.942	-2.838	-2.672
.142	-1.077	-1.918	-2.477	-2.7905	-2.914	-2.898	-2.786	-2.615
.144	-1.074	-1.910	-2.462	-2.7655	-2.879	-2.855	-2.735 -2.685	-2.559 -2.504
.146 .148	-1.072 -1.070	-1.902 -1.895	-2.446 -2.431	-2.7405 -2.716	-2.845 -2.811	-2.812 -2.770	-2.636	-2.504 -2.450
.15	-1.068	-1.888	-2.431	-2.6915	-2.777	-2.728	-2.588	-2.397
.152	-1.065	-1.880	-2.400	-2.667	-2.743	-2.687	-2.541	-2.345
.154	-1.062	-1.872	-2.384	-2.6425	-2.710	-2.646	-2.495	-2.294
.156	-1.060	-1.864	-2.369	-2.6185	-2.677	-2.606	-2.449	-2.244
.158	-1.058	-1.857	-2.353	-2.5945	-2.644	-2.566	-2.403	-2.194
.16	-1.056	-1.850	-2.338	-2.5705	-2.612	-2.526	-2.358	-2.145
.162	-1.053	-1.842	-2.323	-2.547	-2.580	-2.487 -2.448	-2.313	-2.097 -2.050
.164	-1.050 -1.048	-1.835 -1.828	-2.308	-2.5235 -2.500	-2.548 -2.517	-2.448	-2.269 -2.226	-2.003
1	71.040	1 -1.020	-2.293	-2.500	-5.501	-2.410	-2.220	-2.003
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TABLE 3.- Y_k '(τ) FOR VARIOUS VALUES OF k - Concluded

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т	Y ₉ '	Y ₁₀ '	Y ₁₁ '	Y ₁₂ '	Y ₁₃ '	Y ₁₄ '	Y ₁₅ '
0.02	-9.266 -9.083	-10.045 -9.824	-10`.780 -10.517	-11.4705 -11.161	-12.121 -11.764	-12.731 -12.324	-13.301 -12.844
.024 .026	-8.905 -8.730	-9.607 -9.394	-10.259 -10.006	-10.859 -10.564	-11.416 -11.077	-11.929 -11.545	-12.400
.028	-8.558	-9.185	-9.758	-10.277	-10.747	-11.172	-11.970 -11.553
.03	-8.389	-8.980	-9.515	-9.996	-10.426	-10.810	-11.149
.032 .034	-8.223 -8.059	-8.779 -8.582	-9.278 -9.046	-9.722 -9.454	-10.113 -9.808	-10.458 -10.116	-10.757 -10.378
.036	-7.898	-8.388	-8.819	-9.192	-9.511	-9.784	-10.011
.038 .04	-7.739 -7.582	-8.198 -8.012	-8.597 -8.379	-8.936 -8.6865	-9.222 -8.942	-9.462 -9.149	-9.656 -9.313
.042	-7.428	-7.829	-8.166	-8.443	-8.669	-8.845	-8.981
.ዕዛት .ዕዛ6	-7.277 -7.129	-7.650 -7.474	-7.958 -7.754	-8.206 -7.974	-8.403 -8.144	-8.550 -8.264	-8.659 -8.346
.048	-6.983	-7.302	-7.555	-7.749	-7.892	-7.987	-8.043
.05 .052	-6.841 -6.699	-7.134 -6.969	-7.360 -7.169	-7.530 -7.316	-7.647 -7.409	-7.719 -7.459	-7·749 -7·464
.054	-6.560	-6.807	-6.983	-7.107	-7.178	-7.206	-7.189
.056 .058	-6.424 -6.290	-6.648 -6.492	-6.801 -6.623	-6.902 -6.703	-6.953 -6.734	-6.960 -6.721	-6.924 -6.670
.06	-6.160	-6.339	-6.449	-6.5085	-6.520	-6.489	-6.426
.062 .064	-6.030 -5.903	-6.189 -6.042	-6.279 -6.113	-6.319 -6.134	-6.312 -6.110	-6.264 -6.046	-6.189 -5.959
.066	-5.778	-5.898	-5.951	-5.954	-5.914	-5.835	-5.735
.068 .07	-5.655 -5.537	-5.757 -5.620	-5.792 -5.637	-5.779 -5.6085	-5.724 -5.540	-5.632 -5.436	-5.517 -5.304
.072 .074	-5.417	-5.485 ·	-5.485	-5.442	-5.360	-5.246	-5.098
.074	-5.301 -5.187	-5.353 -5.223	-5.337 -5.193	-5.280 -5.1225	-5.185 -5.015	-5.061 -4.881	-4.891 -4.701
.078	-5.075	-5.095	-5.052	-4.969	-4.850	-4.706	-4.518
.082	_4.965 _4.857	-4.970 -4.848	-4.915 -4.781	-4.8195 -4.674	-4.690 -4.535	-4.536 -4.372	-4.361 -4.189
.084	-4.751	-4.728	- 4.650	-4.5315	-4.38¥	-4.372 -4.214	-4.024
.086 .088	-4.647 -4.545	-4.610 -4.495	-4.522 -4.397	-4.393 -4.258	-4.237 -4.095	-4.061 -3.913	-3.866 -3.714
.09	-4.444	I ⊶4.383 I	4.273	-4.1265	-3.957	-3.770	-3.570
.092 .094	-4.345 -4.248	4.273 4.165	-4.154 -4.037	-3-999 -3-874	-3.823 -3.693	-3.632 -3.498	-3.430 -3.294
.096	-4.153	-4.059	-3.923	-3.753	-3.567	-3.368	-3.162
.098	-4.060 -3.969	-3.956 -3.855	-3.812 -3.705	-3.636 -3.522	-3.444 -3.325	-3.242 -3.119	-3.033 -2.908
.102	-3.879	-3.757	-3.600	-3.411	-3.210	-3.001	-2.788
.104 .106	-3.791 -3.705	-3.660 -3.565	-3.497 -3.396	-3.303 -3.198	-3.098 -2.989	-2.887 -2.777	-2.673 -2.563
-108	-3.620	-3-473	-3.297	-3.095	-2.884	-2.671	-2.458
.112	-3.538 -3.455	-3.383 -3.294	-3.201 -3.107	-2.9955 -2.8985	-2.782 -2.684	-2.569 -2.470	-2.357 -2.259
.114	-3.375	-3.207	-3.016	-2.804	-2.589	-2.374	-2.164
.116 .118	-3.297 -3.220	-3.122 -3.039	-2.927 -2.840	-2.712 -2.623	-2.496 -2.406	-2.281 -2.191	-2.072 -1.984
.12	-3.145	-2.959	-2.755	-2.5365	-2.319	-2.105	-1.899
.122 .124	-3.072 -3.000	-2.879 -2.801	-2.672 -2.591	-2.452 -2.372	-2.235 -2.153	-2.022 -1.942	-1.817 -1.738
.126	-2.929	-2.725	-2.512	-2.293	-2.074	-1.864	-1.663
.128 .13	-2.859 -2.790	-2.651 -2.581	-2.436 -2.362	-2.216 -2.1405	-1.997 -1.922	-1.789 -1.717	-1.591 -1.522
.132	-2.723	-2.509	-2.289	-2.068	-1.850	-1.647	-1.455
.134 .136	-2.658 -2.594	-2.440 -2.372	-2.218 -2.149	-1.998 -1.9305	-1.781 -1.714	-1.580 -1.515	-1.391 -1.329
.138	-2.531	-2.306	-2.082	-1.865	-1.650	-1.452	-1.270
.14 .142	-2.469 -2.409	-2.243 -2.177	-2.017 -1.953	-1.801 -1.739	-1.588 -1.527	-1.391 -1.333	-1.213 -1.158
.144	-2.350	-2.115	-1.891	-1.680	-1.468	-1.277	-1.105
.146 .148	-2.292 -2.235	-2.055 -1.997	-1.831 -1.773 .	-1.622 -1.566	-1.411 -1.356	-1.223 -1.171	-1.054 -1.005
.15	-2.176	-1.944	-1.716	-1.5115	-1.303	-1.122	958
.152 .154	-2.124 -2.070	-1.886 -1.832	-1.661 -1.607	-1.460 -1.411	-1.252 -1.202	-1.075 -1.029	913 870
.156	-2.018	-1.779	-1.555	-1.363	-1.154	984	829
.158	-1.967 -1.917	-1.727 -1.676	-1.504 -1.455	-1.317 -1.273	-1.108 -1.063	940 898	790 753
.162	-1.868	-1.626	-1.407	-1.232	-1.020	858	718
.164 .166	-1.820 -1.773	-1.578 -1.531	-1.360 -1.315	-1.192 -1.155	979 939	820 783	685 654
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TABLE 4.- $Y_{-k}^{-1}(\tau)$ FOR VARIOUS VALUES OF k

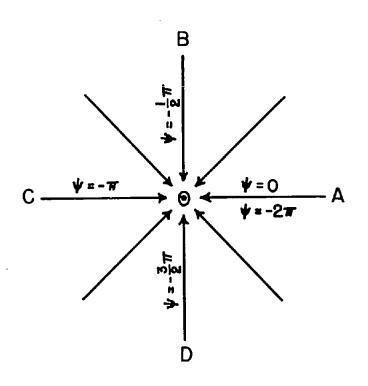
т	Y_1'	Y_2'	Y_3'	Y—,	Y_5'	¥_6'	Y_7'	Y_8'
0.02 .022 .024 .026	1.188 1.182 1.176 1.170	3.418 3.476 3.525 3.569	5.055 5.210 5.367 5.525	6-399 6.589 6.788 6.996	7.895 8.108 8.334 8.574	9.546 9.805 10.075 10.358	11.319 11.631 11.960 12.307	13.197 13.590 14.000 14.428
.028 .03 .032 .034 .036	1.164 1.158 1.152 1.146 1.140	3.610 3.638 3.673 3.704 3.732	5.684 5.844 6.005 6.166	7.213 7.439 7.676 7.922 8.175	8.828 9.097 9.381 9.679	10.656 10.969 11.299 11.648	12.672 13.056 13.459 13.882	14.875 15.342 15.831 16.344
.038 .04 .042 .044	1.134 1.129 1.123 1.117	3.757 3.779 3.799 3.817	6.327 6.488 6.648 6.807 6.965	8.437 8.707 8.985 9.271	9.992 10.320 10.664 11.025 11.405	12.018 12.410 12.825 13.263 13.725	14.326 14.792 15.281 15.798 16.347	16.883 17.451 18.050 18.682 19.349
.046 .048 .05 .052 .054	1.111 1.105 1.100 1.094 1.088	3.833 3.847 3.859 3.869 3.877	7.122 7.277 7.432 7.583 7.732	9.564 9.864 10.172 10.486 10.806	11.803 12.219 12.653 13.106 13.576	14.212 14.726 15.268 15.839 16.441	16.932 17.554 18.215 18.915 19.655	20.054 20.799 21.587 22.423 23.312
.056 .058 .06 .062 .064	1.082 1.076 1.071 1.065 1.059	3.883 3.887 3.889 3.889 3.888	7.879 8.025 8.170 8.312 8.450	11.131 11.461 11.795 12.134 12.477	14.064 14.570 15.094 15.636 16.196	17.076 17.745 18.449 19.187 19.960	20.438 21.265 22.138 23.066 24.051	24.259 25.268 26.342 27.485 28.701
.066 .068 .07 .072 .074	1.053 1.048 1.043 1.037	3.886 3.883 3.878 3.872 3.864	8.584 8.714 8.841 8.965 9.086	12.824 13.173 13.524 13.877 14.232	16.773 17.368 17.979 18.606 19.249	20.768 21.612 22.494 23.413 24.370	25.095 26.196 27.360 28.588 29.882	29.994 31.369 32.829 34.384
.076 .078 .08 .082	1.025 1.020 1.015 1.009	3.854 3.843 3.831 3.818	9.204 9.319 9.430 9.537	14.588 14.944 15.301 15.658	19.907 20.581 21.270 21.973	25.366 26.403 27.482 28.601	31.245 32.679 34.186 35.768	36.039 37.800 39.673 41.662 43.770
.084 .086 .088 .09	1.003 •997 •992 •967 •981	3.804 3.789 3.772 3.754 3.736	9.640 9.739 9.834 9.924 10.010	16.013 16.367 16.719 17.069 17.416	22.688 23.413 24.148 24.892 25.646	29.758 30.950 32.175 33.430 34.724	37.426 39.162 40.976 42.870 44.844	46.002 48.363 50.858 53.492 56.270
.094 .096 .098 .10	.975 .970 .965 .960	3.718 3.699 3.670 3.651 3.628	10.092 10.170 10.244 10.315 10.381	17.760 18.100 18.436 18.768 19.095	26.409 27.180 27.959 28.746 29.538	36.056 37.426 38.834 40.280 41.752	46.900 49.039 51.260 53.563 55.947	59.198 62.280 65.520 68.919 72.480
.104 .106 .108 .11	.949 .944 .939 .934 .928	3.604 3.579 3.553 3.525 3.497	10.442 10.498 10.549 10.596 10.639	19.416 19.732 20.041 20.342 20.636	30.330 31.122 32.914 32.706	43.249 44.771 46.318 47.891	58.411 60.954 63.575 66.272	76.205 80.096 84.154 88.378
.114 .116 .118 .12	.923 .918 .913 .908	3.468 3.439 3.410 3.380	10.677 10.711 10.740 10.765	20.923 21.203 21.475 21.737	33.498 34.288 35.074 35.854 36.627	49.484 51.096 52.727 54.377 56.044	69.044 71.889 74.803 77.781 80.820	92.770 97.331 102.062 106.960 112.021
.122 .124 .126 .128 .13	.902 .897 .892 .887 .882	3.349 3.317 3.285 3.252 3.219	10.785 10.801 10.812 10.818 10.819	21.990 22.233 22.466 22.689 22.903	37.392 38.148 38.893 39.628 40.351	57.724 59.411 61.097 62.773 64.436	83.917 87.069 90.273 93.524 96.817	117.241 122.615 128.137 133.799 139.595
.132 .134 .136 .138	.877 .872 .867 .862 .857	3.185 3.150 3.115 3.079 3.043	10.815 10.808 10.796 10.779 10.758	23.106 23.297 23.476 23.642 23.796	41.060 41.752 42.426 43.080 43.714	66.076 67.753 69.407 71.058 72.698	100.146 103.503 106.879 110.265 113.647	145.520 151.568 157.731 163.991 170.340
.142 .144 .146 .148	.852 .847 .842 .837 .833	3.007 2.970 2.933 2.895 2.856	10.732 10.701 10.666 10.627 10.584	23.937 24.066 24.182 24.286 24.377	44.327 44.918 45.486 46.030 46.549	74.298 75.873 77.403 78.910 80.402	117.029 120.407 123.777 127.134 130.473	176.767 183.258 189.794 196.353 202.915
.152 .154 .156 .158	.828 .823 .818 .813 .808	2.817 2.778 2.738 2.698	10.537 10.485 10.428 10.366	24.454 24.516 24.563 24.596	47.041 47.503 47.933 48.330	81.844 83.233 84.568 85.848	133.784 137.051 140.248 143.333	209.468 215.999 222.504 228.965
.162 .164 .166	.803 .798 .793	2.658 2.618 2.777 2.736	10.298 10.225 10.147 10.064	24.614 24.617 24.605 24.577	48.694 49.024 49.319 49.579	87.076 88.244 89.346 90.376	146.247 148.925 151.298 153.271	235.362 241.671 247.862 253.899

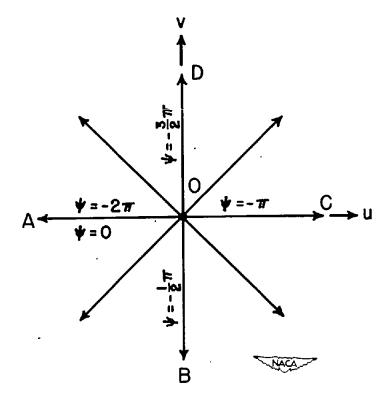
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TABLE 4.- Y_{-k} '(τ) FOR VARIOUS VALUES OF k - Concluded

т	Y_9'	Y_10'	л ^{-л} ,	Y-12'	Y ₋₁₃ '	Y-14'	Y ₋₁₅ '
0.02	15.174	17.250	19.426	21.706	24.092	26.588	29.199
.022	15.656	17.833	20.146	22.562	25.104	27.768	30.564
.024 .026	16.160 16.688	18.451	20.896 21.680	23.455 24.388	26.162 27.270	29.010	32.008 33.535
.028	17.240	19.096 19.772	22.488	25.365	28.433	30.317 31.692	35.149
.03	17.817	20.479	23.335	26.390	29.655	33.140	36.855
.032	18.420	21.219	24.230	27.467	30.941	34.666	38.658
.034 .036	19.051 19.712	21.992 22.800	25.168 26.153	28.599 29.790	32.296 33.724	36.276 37.975	40.563 42.567
.038	20.406	23.648	27.188	31.043	35.230	39.769	44.688
-04	21.135	24.540	28.277	32.362	36.818	41.666	16.935
.042 .044	21.902 22.711	25.478 26.466	29.423 30.630	33.751 35.215	38.493 40.260	43.671 45.791	49.316 51.841
.046	23.566	27.509	31.902	36.759	42.126	48.034	54.520
.048	24.471	28.611	33.244	38.390	44.099	50.409	57.364
.05 .052	25.431 26.447	29.778	34.661 36.161	40.116 41.943	46.187 48.408	52.925 55.595	60.386 63.598
.054	27.525	32.322	37.751	43.879	50.761	58.432	67.014
.056	28.670	33.711	39.440	45.934	53.256	61.450	70.651
.058	29.887	35.187	41.237	48.118	55.906	64.665	74.529
.06 .062	31.184 32.567	36.760 38.437	43.152 45.194	50.444 52.924	58.724 61.729	68.096 71.758	78.673 83.098
.064	34.043	40.228	47 - 374	55.572	64.941	75.669	87.830
-066	35.621	42.144	49.704	58.404	68.382	79.852	92.899
.068 .07	37-309 39.114	44.198 46.402	52.198 54.869	61.437 64.690	72.076 76.0 4 7	84.332 89.140	98.339 104.190
.072	41.045	48.762	57.738	68.186	80.315	94.308	110.484
-074	43.110	51.294	60.826	71.949	84.906	99.880	117.268
.076	45.317	54.01.4 56.938	64.155	76.008	89.852 95.192	105.903 112.426	124.5 <i>97</i> 132.533
.078 .08	47.675 50.196	60.084	67.747 71.626	80.394 85.142	100.974	119.502	141.148
.082	52.891	63.465	75.815	90.284	107.246	127.190	150.506
-084	55.772	67.099	80.338	95.854	114.061	135.551	160.691
.086 .088	58.850 62.136	71.005 75.202	85.220 90.487	101.888 108.436	121.475 129.548	144.648 154.548	171.798 183.934
.09	65.640	79.712	96.165	115.514	138.343	165.321	197.218
.092	69.372	84.555	102.316	123.222	147.932	177.104	211.782
.094 .096	73.342 77.560	89.752 95.325	108.970 116.161	131.602 140.718	158.401 169.839	190.036 204.258	227.786 245.400
.098	82,035	101.295	123.925	150.636	182.340	219.921	264.814
.10	86.778	107.685	132.301	161.424	196.003	237.164	286.239
.102	91.806	114.515	141.331	173.143	210.936	256.114	309.879
.104 .106	97.123 102.738	121.809 129.589	151.056 161.519	185.856 199.629	227.249 245.062	276.014 299.714	335.979 364.809
.108	108.660	137.876	172.764	214.533	264.506	324.685	396.668
.11	114.895	146.690	184.834	230.644	285.722	352.016	431.886
.112 .114	121.454 128.338	156.050 165.976	197.776 211.635	248.082 266.931	308.854 334.043	382.094 415.142	470.796 513.776
.116	135.551	176.486	226.452	287.276	361.439	451.412	561.236
.118	143.096	187.599	242.265	309.204	391.193	491.270	613.621
.12 .122	150.976 159.189	199.331 211.693	259.112 277.029	332.805 358.150	423.459 458.405	534.809 582.358	671.426 735.075
-124	167.732	224.693	296.057	385.312	496.195	634.187	805.018
.126	176.602	238.336	316.230	414.355	537.001 580.096	690.576	881.735
.128 .13	185.796 195.410	252.624 267.558	337.583 360.147	445.355 478.288	580.986 628.331	751.804 818.162	965.736 1057.568
.132	205.244	283.140	383.933	513.378	679.167	890.042	1157.823
-134	215.395	299.371	408.942	550.655	733.612	967.754	1267.107
.136	225.857 236.620	316.250	435.172 462.619	590.165 631.947	791.769 853.717	1051.578 1141.794	1386.030 1515.182
.138 .14	247.671	333.776 351.946	491.271	676.032	919.513	1238.671	1655.123
.142	258.965	370.695	521.138	722.387	989.282	1342.419	1806.364
.1 44	270.476	390.004	552.206 584.458	771.017	1063.136 1141.196	1453.188 1571.058	1969.214 2143.873
.146 .148	282.176 294.035	409.840 430.156	617.864	821.897 874.977	1223.595	1696.029	2330.341
.15	306.019	450.892	652.370	930.184	1310.520	1828.020	2528.419
.152	318.128	472.028	687.900	987.466	1400.675	1967.246	2740.02
.154 .156	330.336 342.614	493.530 515.359	724.354 761.608	1046.750 1107.962	1494.940 1593.145	2113.795 2267.668	2964.45 3201.92
.158	354.932	537.472	799.511	1171.003	1695.141	2428.965	3452.41
.16	367.256	559.821	837.885	1235.774	1800.767	2597.786	3715.74
.162	379.543	582.351.	876.659	1302.046	1909.706 2021.549	2773.500 2955.700	3989.60 4273.90
.164 .166	391.731 403.728	604.991 627.651	915.777 955.198	1369.417 1437.259	2135.644	3143.500	4568.40
	103.150	,	٠	5,,,]	
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SINK

 $w = \phi + i\psi = -\log_e z$

PHYSICAL PLANE

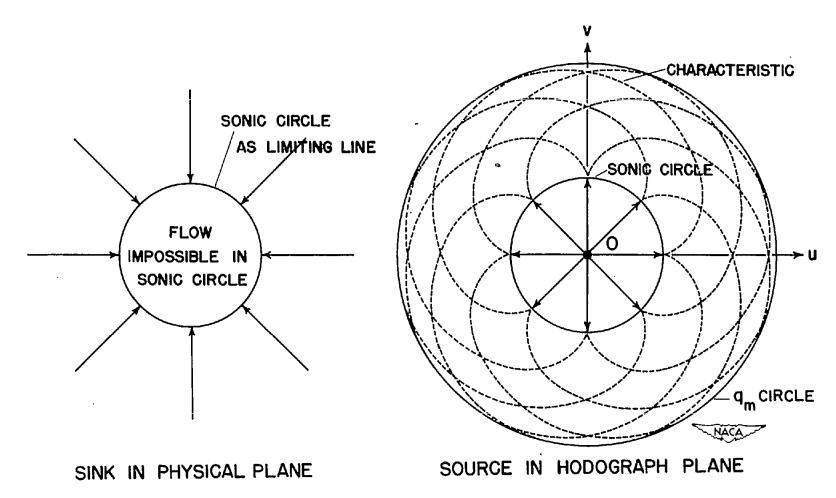
SOURCE

 $w = \phi + i\psi - \log_e \overline{q}$

HODOGRAPH PLANE

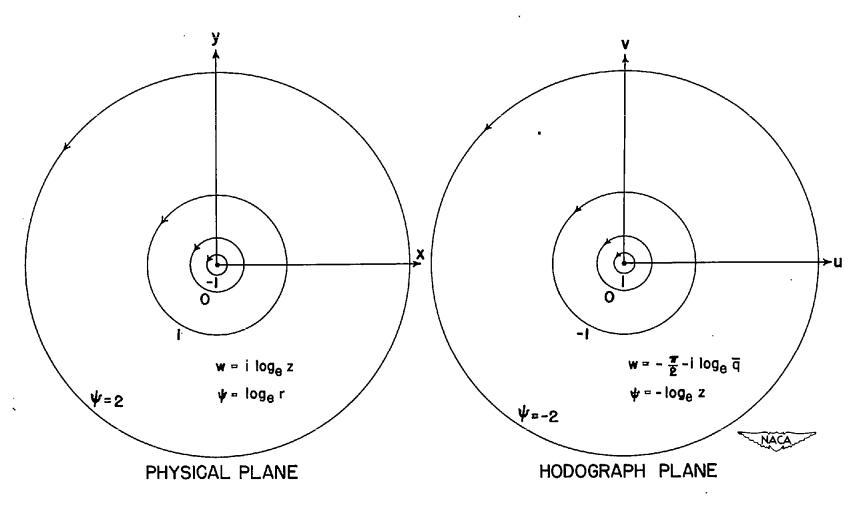
(a) Incompressible flow.

Figure 1.- Sink (negative source) solution.



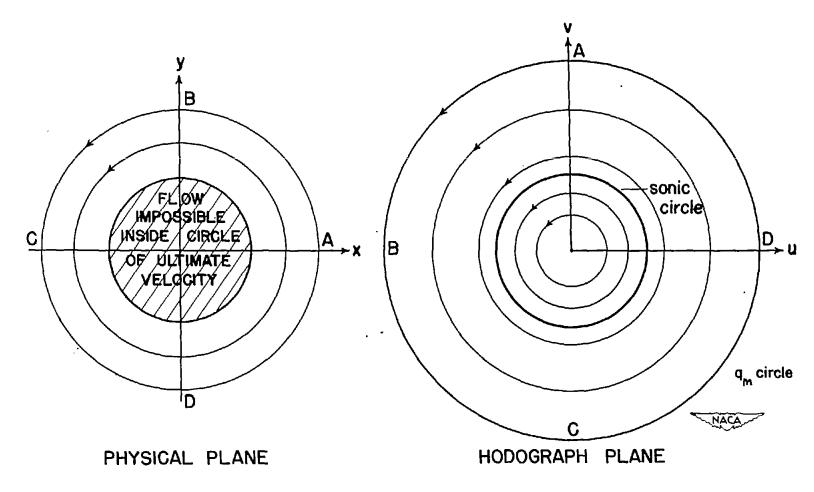
(b) Compressible flow.

Figure 1.- Concluded.



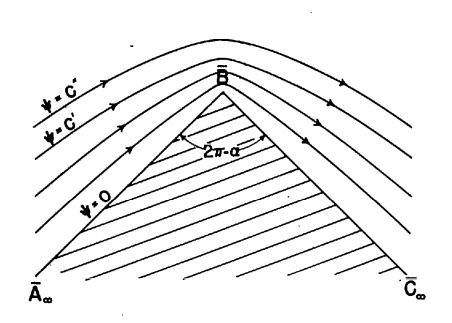
(a) Incompressible flow.

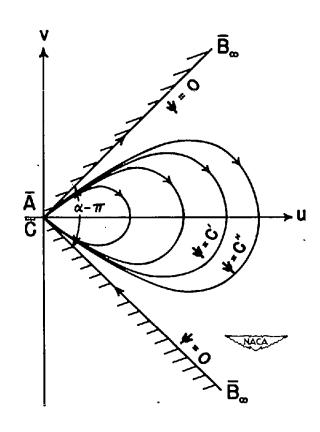
Figure 2.- Vortex in potential field.



(b) Compressible flow.

Figure 2.- Concluded.



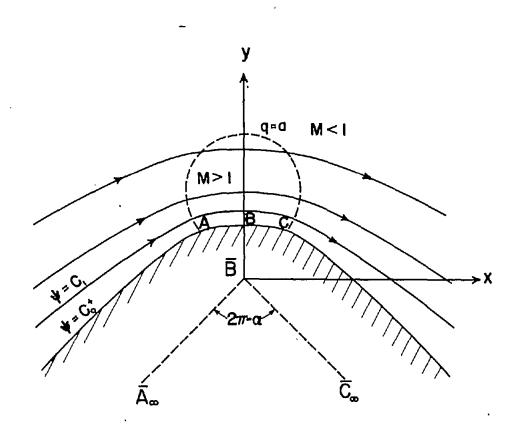


PHYSICAL PLANE

HODOGRAPH PLANE

(a) Incompressible flow.

Figure 3.- Flow around a sharp convex corner (angle, 90°).



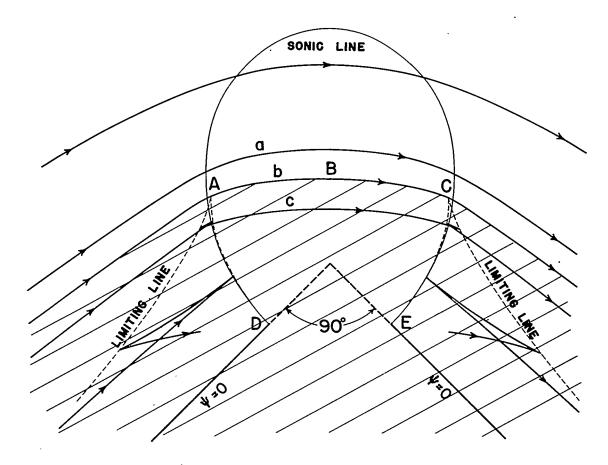
q, q=a

PHYSICAL PLANE

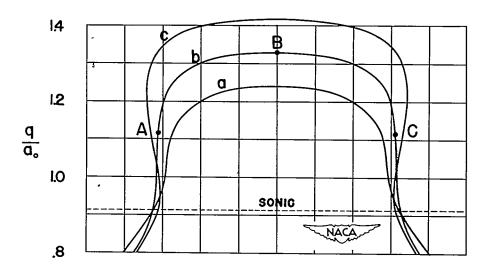
HODOGRAPH PLANE

(b) Compressible flow.

Figure 3.- Concluded.



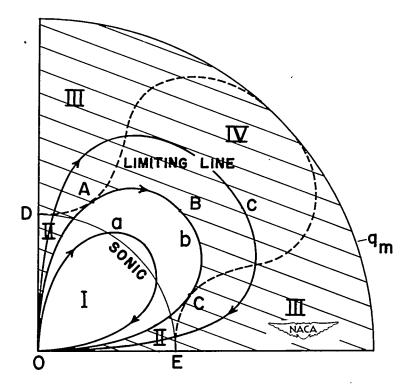
(a) Compressible flow streamlines.



(b) Velocity distribution.

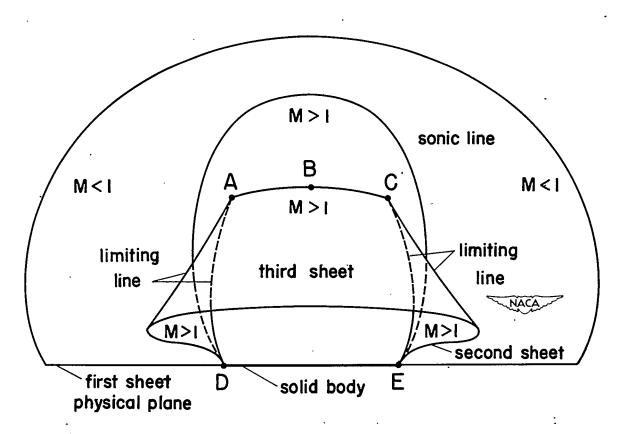
Figure 4.- Details of flow around a corner angle of 90° .

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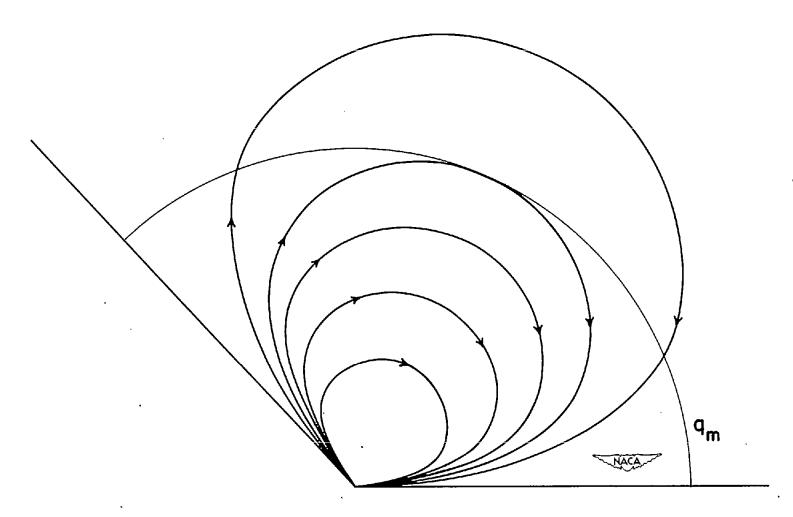
·(c) Hodograph streamlines.

Figure 4.- Continued.



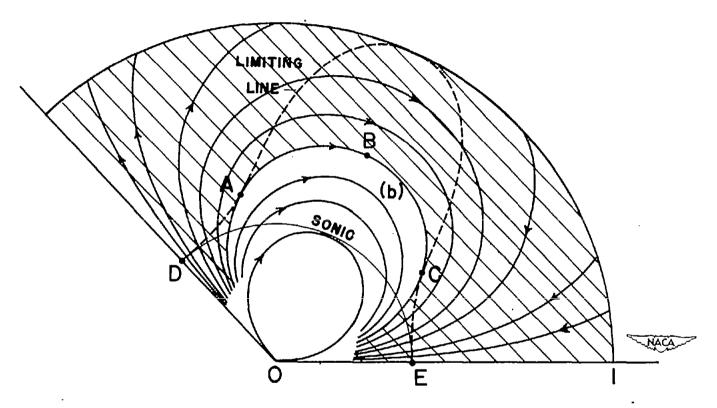
(d) Schematic view of multiple-sheeted Riemann surface in physical plane.

Figure 4.- Concluded.



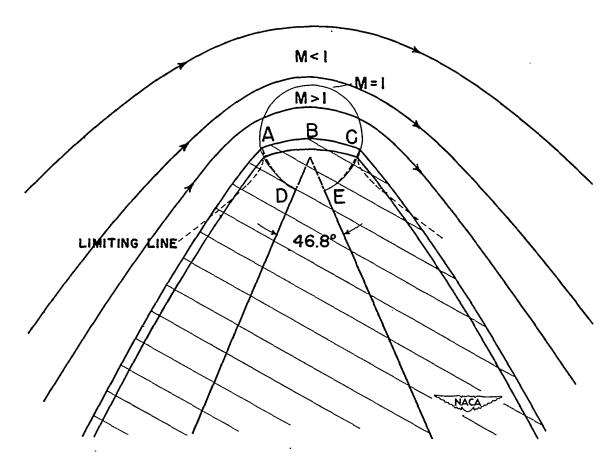
(a) Hodograph streamlines $\left(\frac{q}{q_m} \theta\text{-plane}\right)$ of incompressible flow.

Figure 5.- Details of flow around a corner angle of 46.8°.



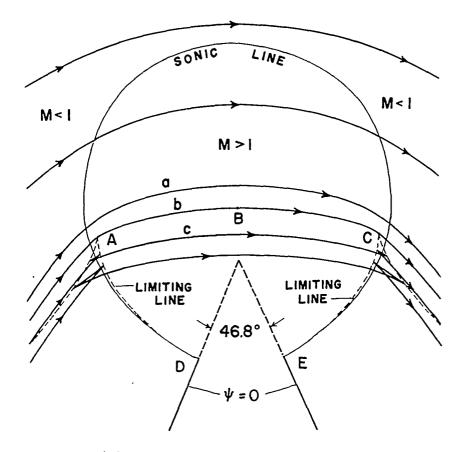
(b) Hodograph streamlines $\left(\frac{\mathbf{q}}{\mathbf{q}_{\mathrm{m}}} \; \theta\text{-plane}\right)$ of compressible flow.

Figure 5.- Continued.

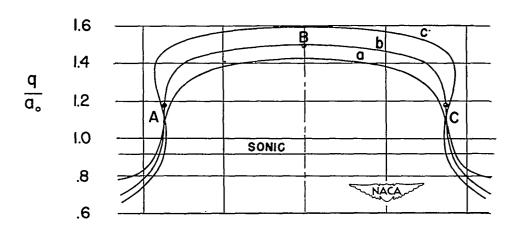


(c) Compressible flow streamlines.

Figure 5.- Continued.



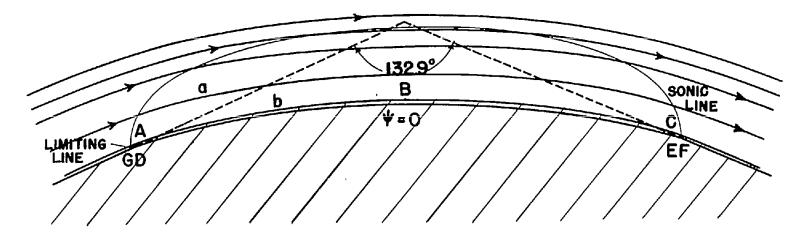
(d) Details of compressible flow.



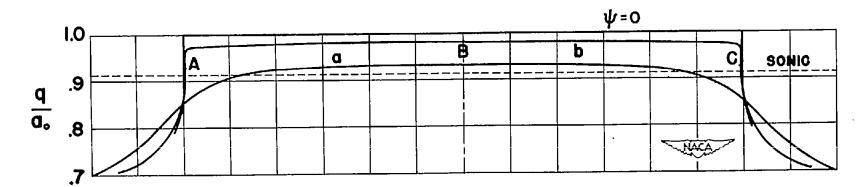
(e) Velocity distribution along some important streamlines.

Figure 5.- Concluded.



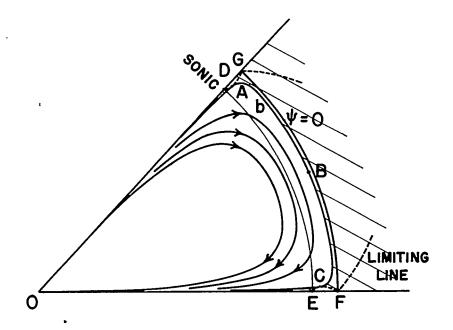


(a) Compressible flow streamlines.

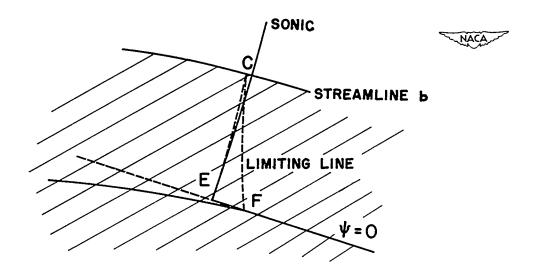


(b) Velocity distribution.

Figure 6.- Details of flow around a corner angle of 132.9°

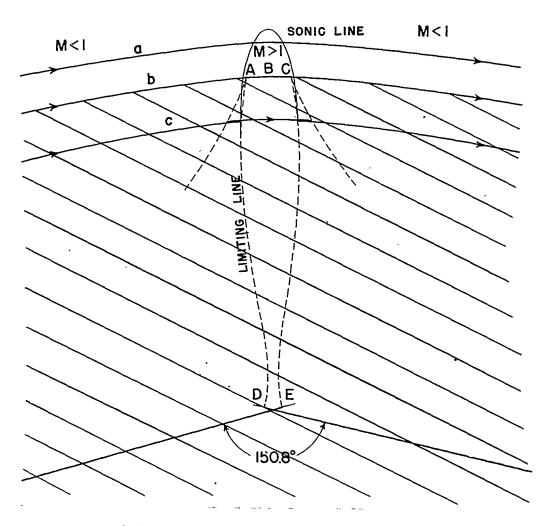


(c) Hodograph streamlines.

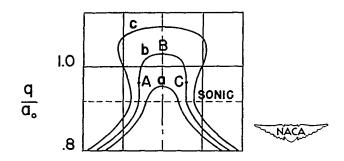


(d) Detail in physical plane.

Figure 6.- Concluded.

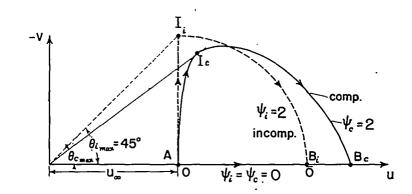


(a) Compressible flow streamlines.

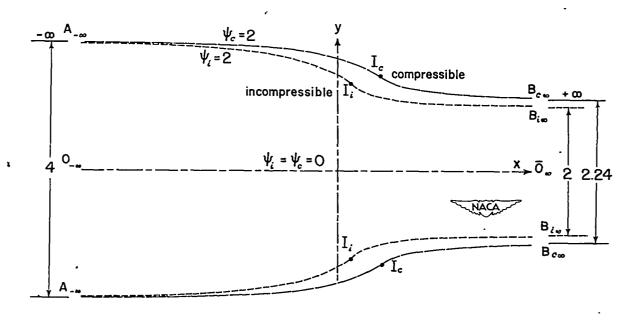


(b) Velocity distribution.

Figure 7.- Details of flow around a corner angle of 150.8°



(a) Hodograph plane.



(b) Physical plane.

Figure 8.- Comparison of compressible and incompressible flow in contracting duct.

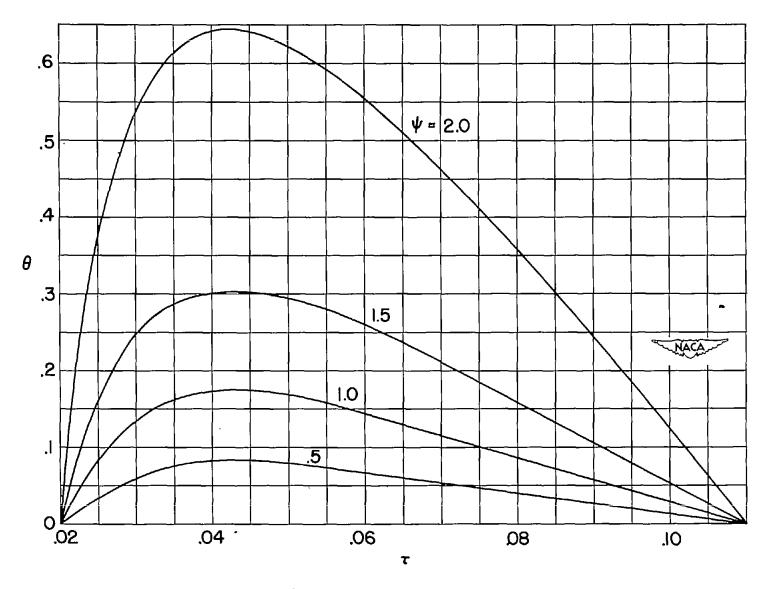
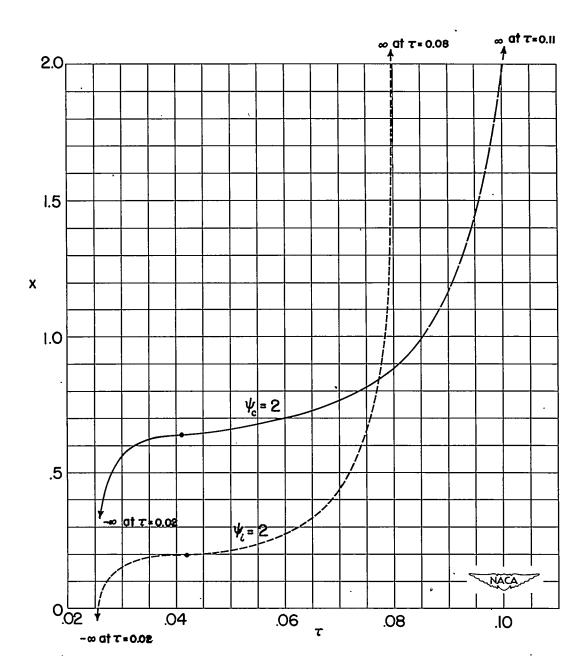
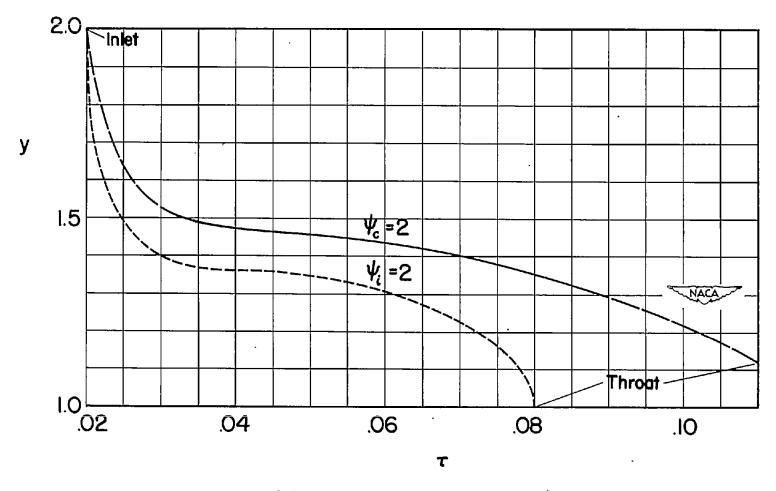


Figure 9.- Streamlines in $\tau\theta$ -plane.



(a) x-coordinates of boundaries.

Figure 10.- Position of boundary streamlines.



(b) y-coordinates of boundaries.

Figure 10.- Concluded.

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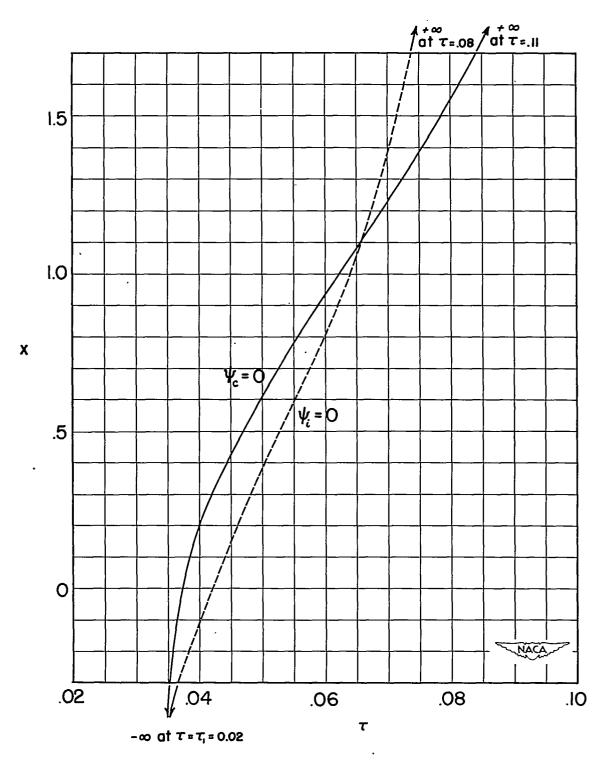


Figure 11.- x-coordinates of center streamlines.

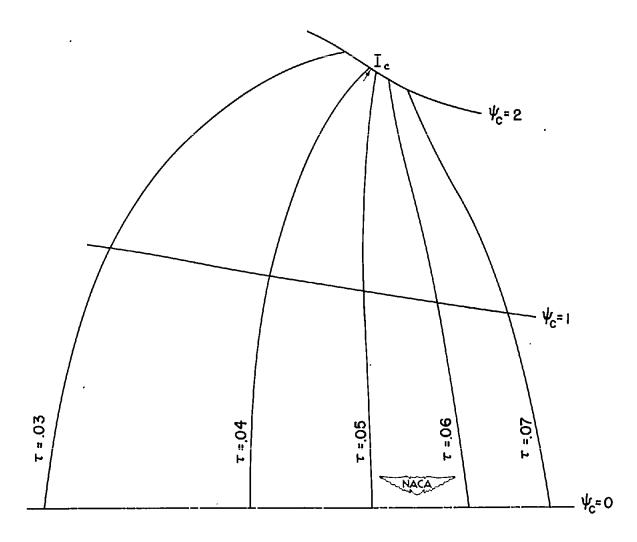


Figure 12.- Detailed compressible flow near inflection point.

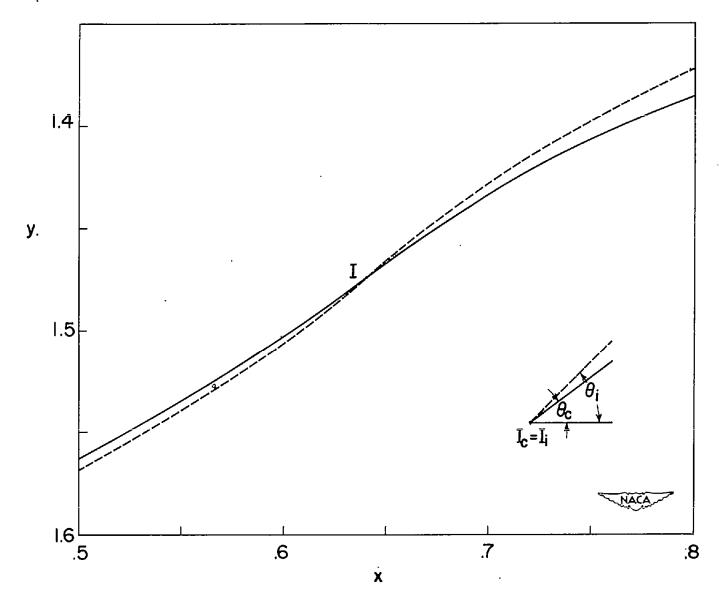


Figure 13.- Comparison of boundaries near inflection point I.